



Flex BASE-MRX (CE)

Radio Control Equipment Instruction Manual



MAGNETEK

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SERVICE INFORMATION

Your New Radio Remote Control System

Thank you for your purchase of Magnetek's Flex Base Radio Remote Equipment Control. Magnetek has set a whole new standard in radio-remote performance, dependability, and value with this unique new line of handheld transmitters.

If your product ever needs modification or service, please contact one of our representatives at the following locations:

U.S. Service Information

For questions regarding service or technical information contact:

1-866-MAG-SERV

(1-866-624-7378)

International Service

262-783-3500

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PRODUCT MANUAL SAFETY INFORMATION

Magnetek, Inc. (Magnetek) offers a broad range of radio remote control products, control products and adjustable frequency drives, and industrial braking systems for overhead material handling applications. This manual has been prepared by Magnetek to provide information and recommendations for the installation, use, operation and service of Magnetek's material handling products and systems (Magnetek Products). Anyone who uses, operates, maintains, services, installs or owns Magnetek Products should know, understand and follow the instructions and safety recommendations in this manual for Magnetek Products.

The recommendations in this manual do not take precedence over any of the following requirements relating to cranes, hoists and lifting devices:

- Instructions, manuals, and safety warnings of the manufacturers of the equipment where the radio system is used,
- Plant safety rules and procedures of the employers and the owners of facilities where the Magnetek Products are being used,
- Regulations issued by the Occupational Health and Safety Administration (OSHA),
- Applicable local, state or federal codes, ordinances, standards and requirements, or
- Safety standards and practices for the overhead material handling industry.

This manual does not include or address the specific instructions and safety warnings of these manufacturers or any of the other requirements listed above. It is the responsibility of the owners, users and operators of the Magnetek Products to know, understand and follow all of these requirements. It is the responsibility of the owner of the Magnetek Products to make its employees aware of all of the above listed requirements and to make certain that all operators are properly trained. **No one should use Magnetek Products prior to becoming familiar with and being trained in these requirements.**

WARRANTY INFORMATION

FOR INFORMATION ON MAGNETEK'S PRODUCT WARRANTIES BY PRODUCT TYPE, PLEASE VISIT WWW.MAGNETEK.COM.

1 Introduction

The **Flex BASE** radio remote control systems are designed for control of industrial equipment and machinery such as overhead traveling cranes, jib cranes, gantry cranes, tower cranes, electric hoists, winches, monorails, conveyor belts, mining equipment, and all other material handling equipment where wireless control is preferred.

Each **Flex BASE** system consists of one transmitter handset and one micro receiver unit. Other standard-equipped accessories include transmitter lanyard, vinyl pouch, pushbutton labels, output cable, and instruction manual CD.

List of notable features includes:

- **62 User-programmable Channels** – advanced synthesized RF controls with 62 built-in programmable channels set via pushbuttons and dipswitches.
- **Wireless Remote Pairing Function** – system pairing and cloning can be done easily and wirelessly.
- **Over 1 Million Unique Address Codes** – each and every Flex BASE system has its own address code and serial number, never repeats.
- **Advanced Controls** – the Flex BASE system utilizes dual advanced microprocessor controls with 32-bit CRC and Hamming Code, which provide ultra-fast, safe, precise, and error-free encoding and decoding.
- **Two-way Transmission** – transmitter and receiver communicate with one another for safe, precise and uninterrupted operation (e.g., receiver status feedbacks).
- **Reliable Pushbuttons** – the pushbuttons are rated for more than 1 million press cycles.
- **Low Power Consumption** – requires only two “AA” alkaline batteries for more than 150 hours of uninterrupted operation between replacements.
- **Durable Nylon and Fiberglass Composite Enclosures** – high resistance to breakage and deformation even in the most abusive environments. The receiver enclosures and output cables are UL94-V0 rated.
- **Fully Sealed Enclosures** – the transmitter and receiver enclosures are IP66 rated.
- **Full Compliance** – all systems fully comply with the FCC Part-15 Rules and European Safety Standards.
- **Other Optional Accessories and Features** – transmitter magnet mount, transmitter belt clip, transmitter waist belt, transmitter rubber guards, charging station, external antenna kit, and many others.

2 Radio Controlled Safety

WARNINGS and CAUTIONS

Throughout this document WARNING and CAUTION statements have been deliberately placed to highlight items critical to the protection of personnel and equipment.



WARNING

WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.



CAUTION

CAUTION indicates a potentially hazardous situation which, if not avoided, could result in minor or moderate injury. It may also be used to alert against unsafe practices.

NOTE: A NOTE statement is used to notify people of installation, operation, programming, or maintenance information that is important, but not hazard-related.

WARNINGS and CAUTIONS SHOULD NEVER BE DISREGARDED.

The safety rules in this section are not intended to replace any rules or regulations of any applicable local, state, or federal governing organizations. Always follow your local lockout and tagout procedure when maintaining any radio equipment. The following information is intended to be used in conjunction with other rules or regulations already in existence. It is important to read all of the safety information contained in this section before installing or operating the Radio Control System.

2.1 Critical Installation Considerations



Prior to installation and operation of this equipment, read and develop an understanding of the contents of this manual and the operation manual of the equipment or device to which this equipment will be interfaced. Failure to follow this warning could result in serious injury or death and damage to equipment.

All equipment must have a mainline contactor installed and all tracked cranes, hoists, lifting devices and similar equipment must have a brake installed. Failure to follow this warning could result in serious injury or death and damage to equipment.

An audible and/or visual warning means must be provided on all remote controlled equipment as required by code, regulation, or industry standard. These audible and/or visual warning devices must meet all governmental requirements. Failure to follow this warning could result in serious injury or death and damage to equipment.

Follow your local lockout tagout procedure before maintaining any remote controlled equipment. Always remove all electrical power from the crane, hoist, lifting device or similar equipment before attempting any installation procedures. De-energize and tagout all sources of electrical power before touch-testing any equipment. Failure to follow this warning could result in serious injury or death and damage to equipment.

The direct outputs of this product are not designed to interface directly to two state safety critical maintained functions, i.e., magnets, vacuum lifts, pumps, emergency equipment, etc. A mechanically locking intermediate relay system with separate power considerations must be provided. Failure to follow this warning could result in serious injury or death or damage to equipment.

2.2 General

Radio controlled material handling equipment operates in several directions. Cranes, hoists, lifting devices and other material handling equipment can be large, and operate at high speeds. Quite frequently, the equipment is operated in areas where people are working in close proximity to the material handling equipment. **The operator must exercise extreme caution at all times.** Workers must constantly be alert to avoid accidents. The following recommendations have been included to indicate how careful and thoughtful actions may prevent injuries, damage to equipment, or even save a life.

2.3 Persons Authorized to Operate Radio Controlled Cranes

Only properly trained persons designated by management should be permitted to operate radio controlled equipment.

Radio controlled cranes, hoists, lifting devices and other material handling equipment should not be operated by any person who cannot read or understand signs, notices and operating instructions that pertain to the equipment.

Radio controlled equipment should not be operated by any person with insufficient eyesight or hearing or by any person who may be suffering from a disorder or illness that may cause them to lose control of the equipment, is taking any medication that may cause loss of equipment control, or is under the influence of alcohol or drugs.

2.4 Safety Information and Recommended Training for Radio Controlled Equipment Operators

Anyone being trained to operate radio controlled equipment should possess as a minimum the following knowledge and skills before using the radio controlled equipment.

The operator should:

- have knowledge of hazards pertaining to equipment operation
- have knowledge of safety rules for radio controlled equipment
- have the ability to judge distance of moving objects
- know how to properly test prior to operation
- be trained in the safe operation of the radio transmitter as it pertains to the crane, hoist, lifting device or other material handling equipment being operated
- have knowledge of the use of equipment warning lights and alarms
- have knowledge of the proper storage space for a radio control transmitter when not in use
- be trained in transferring a radio control transmitter to another person
- be trained how and when to report unsafe or unusual operating conditions
- test the transmitter emergency stop and all warning devices prior to operation; testing should be done on each shift, without a load
- be thoroughly trained and knowledgeable in proper and safe operation of the crane, hoist, lifting device, or other material handling equipment that utilizes the radio control
- know how to keep the operator and other people clear of lifted loads and to avoid “pinch” points
- continuously watch and monitor status of lifted loads
- know and follow cable and hook inspection procedures
- know and follow the local lockout and tagout procedures when servicing radio controlled equipment
- know and follow all applicable operating and maintenance manuals, safety procedures, regulatory requirements, and industry standards and codes

The operator shall not:

- lift or move more than the rated load
- operate the material handling equipment if the direction of travel or function engaged does not agree with what is indicated on the controller
- use the crane, hoist or lifting device to lift, support or transport people
- lift or carry any loads over people
- operate the crane, hoist or lifting device unless all persons, including the operator, are and remain clear of the supported load and any potential pinch points
- operate a crane, hoist or lifting device when the device is not centered over the load
- operate a crane, hoist or lifting device if the chain or wire rope is not seated properly in the sprockets, drum or sheave
- operate any damaged or malfunctioning crane, hoist, lifting device or other material handling equipment
- change any settings or controls without authorization and proper training
- remove or obscure any warning or safety labels or tags
- leave any load unattended while lifted
- leave power on the radio controlled equipment when the equipment is not in operation

- operate any material handling equipment using a damaged controller because the unit may be unsafe
- operate manual motions with other than manual power
- operate radio controlled equipment when low battery indicator is on



WARNING

The operator should not attempt to repair any radio controller. If any product performance or safety concerns are observed, the equipment should immediately be taken out of service and be reported to the supervisor. Damaged and inoperable radio controller equipment should be returned to Magnetek for evaluation and repair. Failure to follow this warning could result in serious injury or death and damage to equipment.

2.5 Transmitter Unit

Transmitter switches should never be mechanically blocked on or off. When not in use, the operator should turn the transmitter off. A secure storage space should be provided for the transmitter unit, and the transmitter unit should always be placed there when not in use. This precaution will help prevent unauthorized people from operating the material handling equipment.

Spare transmitters should be stored in a secure storage space and only removed from the storage space after the current transmitter in use has been turned off, taken out of the service area and secured.

2.6 Pre-Operation Test

At the start of each work shift, or when a new operator takes control of the crane, operators should perform, at a minimum, the following steps before making lifts with any crane or hoist:

Test all warning devices.

Test all direction and speed controls.

Test the transmitter emergency stop.

2.7 Handling Batteries



WARNING

Know and follow proper battery handling, charging and disposal procedures. Improper battery procedures can cause batteries to explode or do other serious damage. Failure to follow this warning could result in serious injury or death and damage to equipment.

- Use only batteries approved by Magnetek for the specific product.
- Do not dispose of a battery pack in fire; it may explode.
- Do not attempt to open the battery pack.

- Do not short circuit the battery.
- Keep the battery pack environment cool during storage (i.e., not in direct sunlight or close to a heating source).

2.8 Optional Rechargeable Battery Charging

- For those transmitters equipped with rechargeable batteries and battery chargers, all users shall be familiar with the instructions of the charger before attempting to use.
- Do not attempt to charge non-rechargeable battery packs in the charger.
- Avoid charging partially discharged rechargeable batteries to help prolong battery cycle life.
- Do not charge batteries in a hazardous environment.
- Keep the battery pack environment cool during charging (i.e., not in direct sunlight or close to a heating source).
- Do not short the charger.
- Do not attempt to charge a damaged battery.
- Use only Magnetek approved chargers for the appropriate battery pack.
- Do not attempt to use a battery that is leaking, swollen or corroded.
- Charger units are not intended for outdoor use. Only use charger units indoors.

2.9 Battery Disposal

Before disposing of batteries consult local and governmental regulatory requirements for proper disposal procedure.

2.10 Crane/Lifting Device Specific Warnings



All equipment must have a mainline contactor installed and all tracked cranes, hoists, lifting devices and similar equipment must have a brake installed. Failure to follow this warning could result in serious injury or death and damage to equipment.

An audible and/or visual warning means must be provided on all remote controlled equipment as required by code, regulation, or industry standard. These audible and/or visual warning devices must meet all governmental requirements. Failure to follow this warning could result in serious injury or death and damage to equipment.

The direct outputs of this product are not designed to interface directly to two state safety critical maintained functions, i.e., magnets, vacuum lifts, pumps, emergency equipment, etc. A mechanically locking intermediate relay system with separate power considerations must be provided. Failure to follow this warning could result in serious injury or death or damage to equipment.

Cranes, hoists, lifting devices and other material handling equipment can be large, and can operate at high speeds.

The operator should:

- continuously watch and monitor status of lifted loads.
- know and follow cable and hook inspection procedures.

The operator shall not:

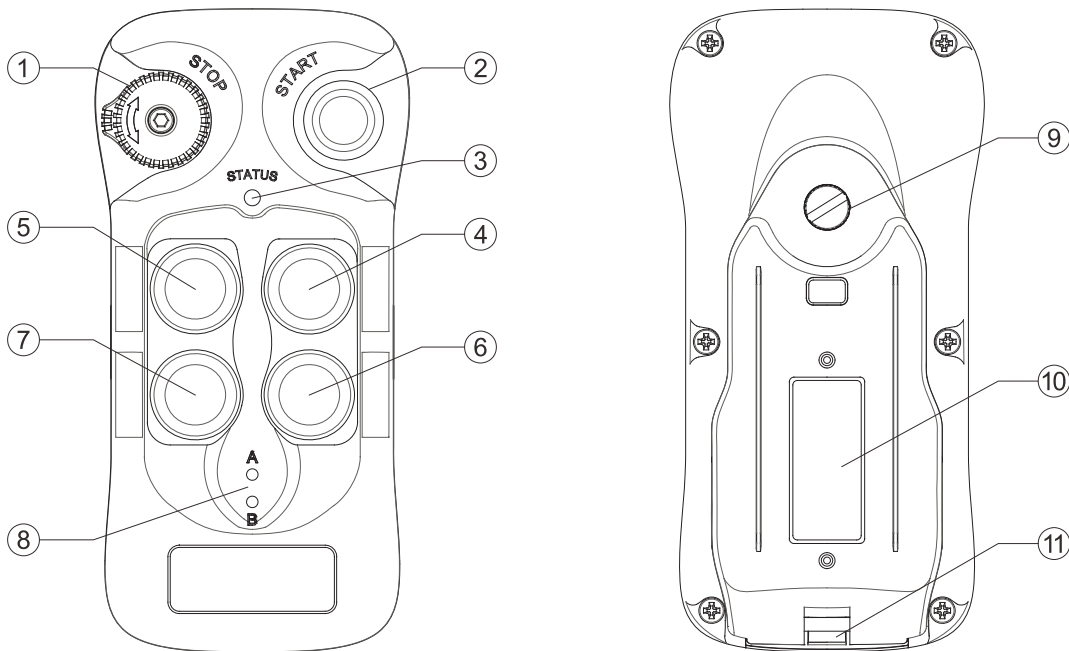
- lift or move more than the rated load.
- use the crane, hoist or lifting device to lift, support or transport people.
- lift or carry any loads over people.
- operate the crane, hoist or lifting device unless all persons, including the operator, are and remain clear of the supported load and any potential pinch points.
- operate a crane, hoist or lifting device when the device is not centered over the load.
- operate a crane, hoist or lifting device if the chain or wire rope is not seated properly in the sprockets, drum or sheave.
- leave any load unattended while lifted.

3 General System Information

3.1 Transmitter

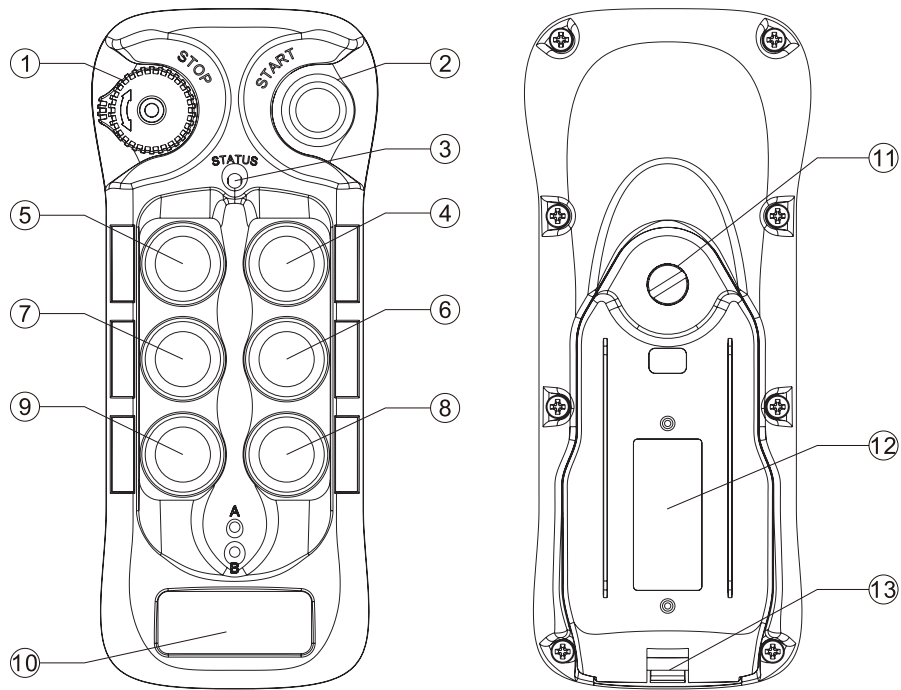
3.1.1 External Illustration

4BASE



- | | | | |
|----|----------------------|-----|--|
| 1. | STOP Button | 7. | Pushbutton 4 (PB4) |
| 2. | START Button | 8. | A/B LED Indicators |
| 3. | Status LED Indicator | 9. | Battery Cover Screw |
| 4. | Pushbutton 1 (PB1) | 10. | System Information |
| 5. | Pushbutton 2 (PB2) | 11. | Lanyard and Waist Belt Attachment Slot |
| 6. | Pushbutton 3 (PB3) | | |

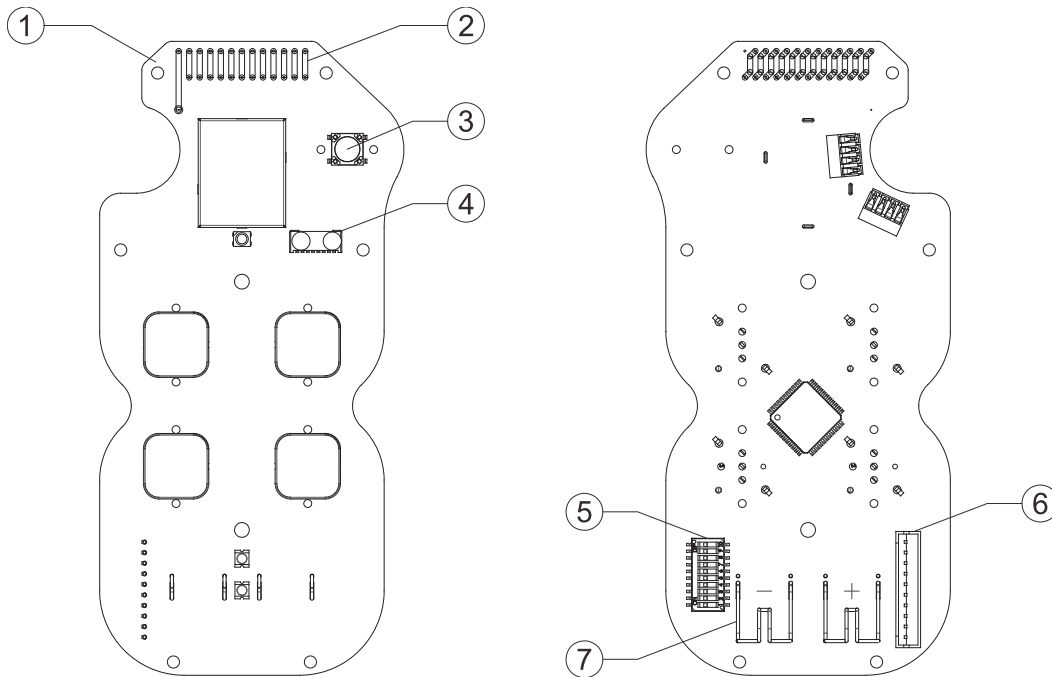
6BASE



- | | |
|-------------------------|--|
| 1. STOP Button | 8. Pushbutton 5 (PB5) |
| 2. START Button | 9. Pushbutton 6 (PB6) |
| 3. Status LED Indicator | 10. A/B LED Indicators |
| 4. Pushbutton 1 (PB1) | 11. Battery Cover Screw |
| 5. Pushbutton 2 (PB2) | 12. System Information |
| 6. Pushbutton 3 (PB3) | 13. Lanyard and Waist Belt Attachment Slot |
| 7. Pushbutton 4 (PB4) | |

3.1.2 Internal Illustration

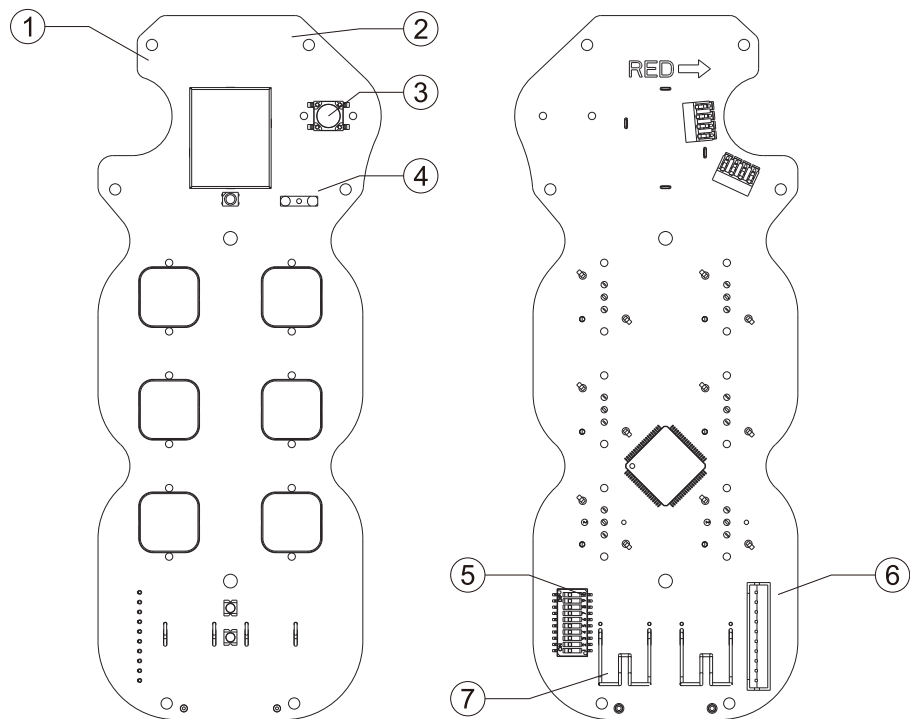
4BASE



1. RF/Encoder Board
2. Antenna
3. START Button
4. Infrared Sensors

5. Function Dipswitch
6. Programming Port
7. Battery Contacts

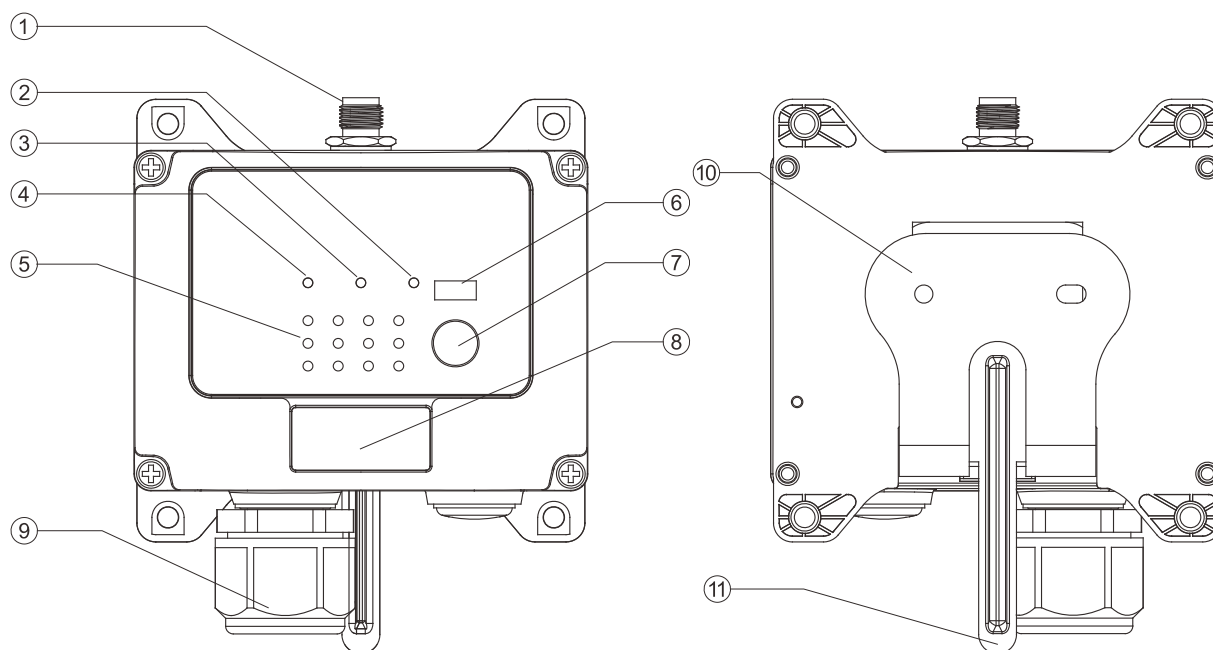
6BASE



- | | | | |
|----|------------------|----|--------------------|
| 1. | RF/Encoder Board | 5. | Function Dipswitch |
| 2. | Antenna | 6. | Programming Port |
| 3. | START Button | 7. | Battery Contacts |
| 4. | Infrared Sensors | | |

3.2 Receiver

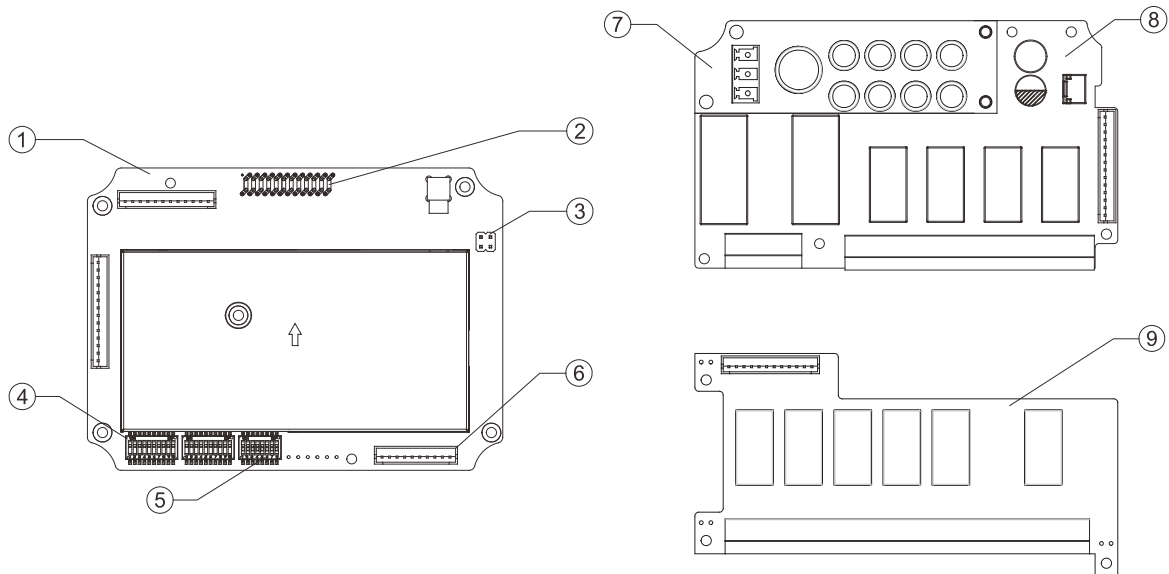
3.2.1 External Illustration



1. External TNC Antenna Port
2. COM LED Indicator
3. Status LED Indicator
4. Power LED Indicator
5. Output Relay LED Indicators
6. Infrared Sensors

7. Remote Pairing Button
8. System Information
9. Cord Grip
10. Mounting Bracket (optional)
11. Mounting Bracket Release

3.2.2 Internal Illustration



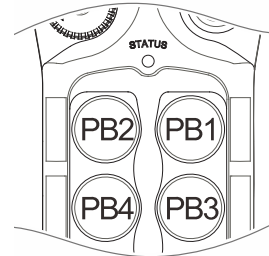
- | | | | |
|----|-------------------------|----|-------------------|
| 1. | RF/Decoder Board | 6. | Programming Port |
| 2. | Internal Antenna | 7. | Power Transformer |
| 3. | INT/EXT Antenna Jumpers | 8. | Lower Relay Board |
| 4. | Function Dipswitches | 9. | Upper Relay Board |
| 5. | Channel Dipswitch | | |

4 Function Settings

4.1 Transmitter

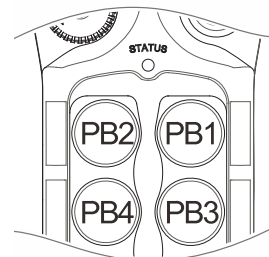
4.1.1 Transmitter Firmware Version

1. Press down the STOP button (transmitter power off).
2. Press and hold PB1 and PB3 at the same time.
3. Reset the STOP button by rotating it clockwise or counterclockwise. It will pop up (transmitter power on).
4. Release PB1 and PB3 at the same time. The Status LED displays firmware version with red, green and orange blinks.
5. Exit Firmware Version mode by pressing down the STOP button (transmitter power off).



4.1.2 Transmitter Channel Settings

1. Press down the STOP button (transmitter power off).
2. Press and hold PB1 and PB2 at the same time.
3. Reset the STOP button by rotating it clockwise or counterclockwise. It will pop up (transmitter power on).
4. Release PB1 and PB2 at the same time. The Status LED displays current channel setting with red and green blinks. A green blink represents the tens (+10) and a red blink represents the units (+1). For example, 1 green blink followed by 5 red blinks is channel 15. LED-A also lights up during channel setting mode.
5. Change transmitter channel by pressing PB1 to increment the units (+1) and PB2 to increment the tens (+10). For example, pressing PB2 two times and then PB1 four times is channel 24 (Status LED blinks 2 greens and 4 reds). Make sure the newly selected channel is shown on the Status LED before proceeding to the next step.
6. Transfer the newly selected channel to the receiver by pressing and holding the START button until the Status LED turns to solid green (transfer complete). Press down the STOP button if solid green is not shown on the Status LED after more than 10 seconds (transfer incomplete); the transmitter will revert back to its previous channel setting. Make sure the receiver power is turned on and is within the operating distance during the entire process. **Skip step 6 if changing receiver channel is not required.**
7. Exit Channel Setting mode by pressing down the STOP button (transmitter power off).



NOTE: When selecting a new channel, make sure each button press does not exceed 3 seconds.

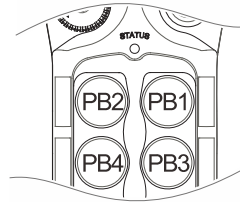
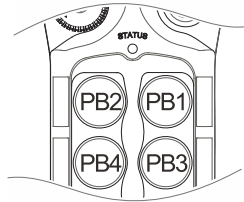
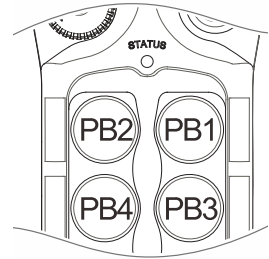
Important Note:

Step 6 illustrated above is strictly required if you are intending to change the entire system channel (both transmitter and receiver). The entire system will no longer work if step 6 is skipped because the transmitter and receiver channels are now different (new vs. old). In this case you would have to redo steps 1-4 and step 6 to transfer the newly selected transmitter channel to the receiver.

4.1.3 Remote Pairing

A. Transmitter-to-Transmitter Pairing:

1. Press down the STOP button (transmitter power off).
2. Press and hold PB1 and PB3 at the same time.
3. Reset the STOP button by rotating it clockwise or counterclockwise. It will pop up (transmitter power on).
4. Release PB1 and PB3 at the same time (entered Remote Pairing mode). The Status LED displays firmware version with red, green and orange blinks.
5. Output data (original transmitter) by pressing and holding PB2 (Status LED off and LED-B solid red).
6. Receive data (new transmitter) by pressing and holding PB1 (Status LED blinks green and LED-A solid red).
7. When the Status LED (receiving data end) turns to solid green while both pushbuttons are still pressed down, the pairing is completed.
8. Exit Remote Pairing mode by pressing down the STOP button (transmitter power off).



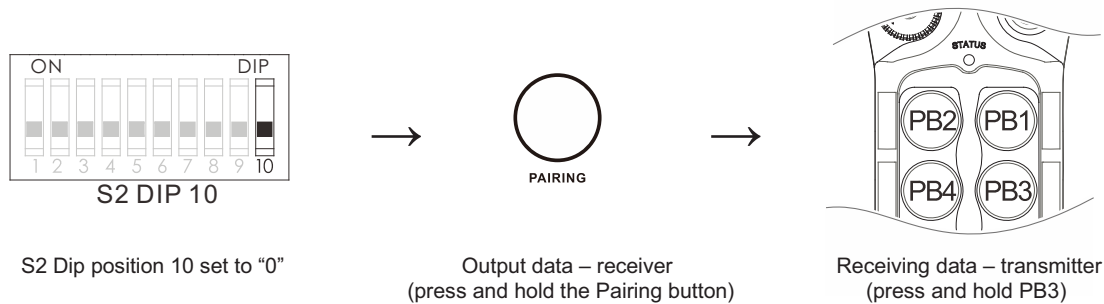
Output data – original transmitter
(press and hold PB2)

Receive data – new transmitter
(press and hold PB1)

NOTE: During remote pairing make sure the distance between the two transmitters is no more than 1 meter.

B. Receiver-to-Transmitter Pairing:

S2 Dip position 10 set to “0” (down): After the transmitter enters the Remote Pairing mode, output receiver data by pressing and holding the PAIRING button located on the receiver cover and receive data by pressing and holding PB3 on the transmitter, both at the same time. When the transmitter Status LED turns to solid green while both pushbuttons are still pressed down, the pairing is completed.

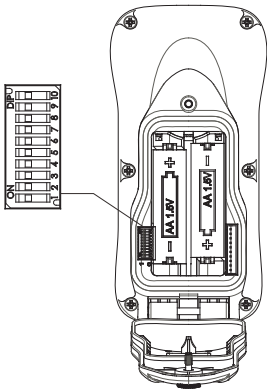


S2 Dip position 10 set to “1” (up): After the transmitter enters the Remote Pairing mode, press and hold PB3 on the transmitter until the Status LED turns to solid green, indicating the pairing is complete. Make sure the transmitter and receiver are within 10 meters from one another and that no other active receivers are nearby during the pairing process. During pairing process the receiver MAIN relays must be deactivated (relay open).

4.1.4 Transmitter Start Function Settings

When transmitter goes into sleep mode the system is temporarily deactivated (MAIN relays opened). Press the START button (default) or set it to have any pushbutton reactivate the system (MAIN relays closed).

	Dipswitch Settings	Function
1	xxxxxxxx0	START Reactivation
2	xxxxxxxx1	Any Button Reactivation



4.1.5 Transmitter Inactivity Timer Settings

Set how long the transmitter enters the sleep mode when not in use (pushbutton not pressed). When transmitter goes into sleep mode the receiver MAIN relays are deactivated. The default timeout setting is 5 minutes.

	Dipswitch Settings	Time		Dipswitch Settings	Time
1	xxx000xxxx	1 minute	5	xxx100xxxx	10 minutes
2	xxx001xxxx	20 seconds	6	xxx101xxxx	30 minutes
3	xxx010xxxx	3 minutes	7	xxx110xxxx	60 minutes
4	xxx011xxxx	5 minutes	8	xxx111xxxx	Constant On (sleep mode disabled)

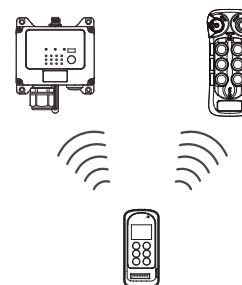
4.1.6 Transmitter Output Power Settings

1mW offers the shortest operating range with lowest battery consumption while 10mW offers the longest operating range with highest battery consumption. The default output power is 2mW.

	Dipswitch Settings	Output Power		Dipswitch Settings	Output Power
1	000xxxxxxx	1mW	5	100xxxxxxx	5mW
2	001xxxxxxx	2mW	6	101xxxxxxx	6mW
3	010xxxxxxx	3mW	7	110xxxxxxx	8mW
4	011xxxxxxx	4mW	8	111xxxxxxx	10mW

4.1.7 Infrared Programming

Other custom functions and settings not listed in this manual can be programmed via the infrared IR programmer unit, such as the system serial number, channel, frequency range, new and updated functions, plus many others. Please contact a Magnetek representative for more details.



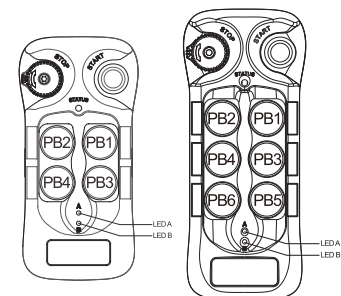
4.1.8 Pushbutton Function Settings

1. Press down the STOP button (transmitter power off).
2. Press and hold PB3 and PB4 at the same time.
3. Reset the STOP button by rotating it clockwise or counterclockwise. It will pop up (transmitter power on).
4. Release PB3 and PB4 at the same time (entered Pushbutton Function mode). LED-B lights up during pushbutton function setting mode.

5. The Status LED displays current pushbutton function setting with orange, green and red blinks. An orange blink represents the hundreds (+100), a green blink represents the tens (+010) and a red blink represents the units (+001). For example, **1** orange blink followed by **2** green blinks and **5** red blinks is pushbutton function no. **125**. Pushbutton function number with "0" is represented by no orange, green or red blink. For example, **1** orange blink followed by **5** red blinks is pushbutton function no. **105**.
6. Set pushbutton function number by pressing PB3 to increment the hundreds (+100), PB2 to increment the tens (+010), PB1 to increment the units (+001), and PB4 to reset (000 - solid orange). For example, press PB3 one time, PB2 four times, and PB1 six times for pushbutton function no. **146** (Status LED blinks **1** orange, **4** greens and **6** reds).
7. Exit Pushbutton Function mode by pressing down the STOP button (transmitter power off).

4.1.8.1 Toggled Pushbutton with LED Indication – Standard Right/Left Pushbutton Configuration

Set pushbutton toggled function (latching output relay) with LED indications. LED A and LED B shown inside the shaded box illustrates which LED on the transmitter lights up when the designated pushbutton is pressed.



4BASE:

Function Number	Display Type	PB1	PB2	PB3	PB4
1	1 Red	LED A	Normal	Normal	Normal
2	2 Reds	Normal	LED B	Normal	Normal
3	3 Reds	Normal	Normal	LED A	Normal
4	4 Reds	Normal	Normal	Normal	LED B
13	1 Green + 3 Reds	LED A	LED B	Normal	Normal
14	1 Green + 4 Reds	Normal	Normal	LED A	LED B

* PB1...PB4 → Pushbutton number.

* Normal → Normal momentary contact.

* LED A & LED B → Pushbutton toggled function with designated LED indication.

6BASE:

Function Number	Display Type	PB1	PB2	PB3	PB4	PB5	PB6
1	1 Red	LED A	Normal	Normal	Normal	Normal	Normal
2	2 Reds	Normal	LED B	Normal	Normal	Normal	Normal
3	3 Reds	Normal	Normal	LED A	Normal	Normal	Normal
4	4 Reds	Normal	Normal	Normal	LED B	Normal	Normal
5	5 Reds	Normal	Normal	Normal	Normal	LED A	Normal
6	6 Reds	Normal	Normal	Normal	Normal	Normal	LED B
13	1 Green + 3 Reds	LED A	LED B	Normal	Normal	Normal	Normal
14	1 Green + 4 Reds	Normal	Normal	LED A	LED B	Normal	Normal
15	1 Green + 5 Reds	Normal	Normal	Normal	Normal	LED A	LED B

* PB1...PB6 → Pushbutton number.

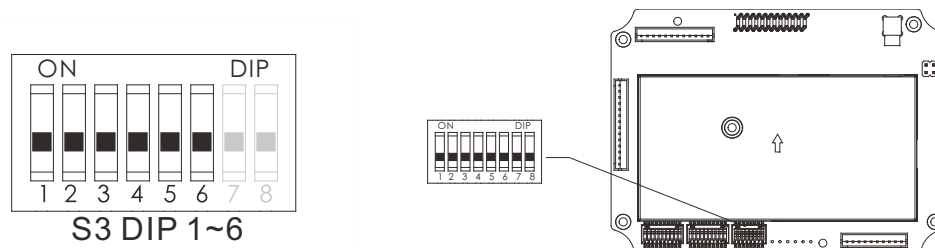
* Normal → Normal momentary contact.

* LED A & LED B → Pushbutton toggled function with designated LED indication.

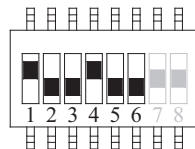
4.2 Receiver

4.2.1 Receiver Channel Settings

Set the receiver channel by configuring the S3 channel dipswitch located on the RF/decoder board. Only the first 6 dip positions are used for channel programming. The system channels table in **Section 4.2.6 on page 31** illustrates which dipswitch setting corresponds to which channel. Once the receiver channel is altered, be sure to change the transmitter channel as well. The channel on both transmitter and receiver must be identical in order for the system to work (**see Section 4.1.2 on page 18**).



Example:



Top position → "1"
Bottom position → "0"

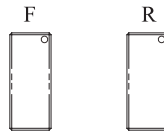
The above dipswitch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table in **Section 4.2.6 on page 31**.

4.2.2 Output Relay Configurations

4.2.2.1 Output Relay Types

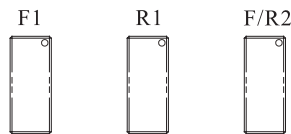
1. **2 output relays per motion – single speed only**

Output relays with Forward (F) and Reverse (R) 1st speed only.



2. **3 output relays per motion – shared 2nd speed output relay**

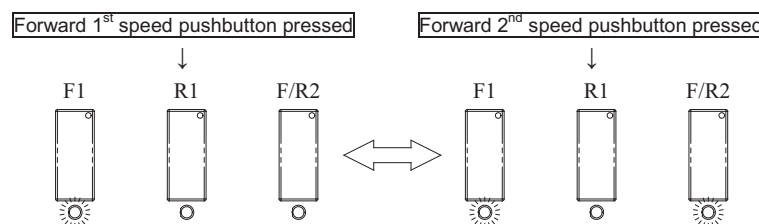
Output relays with Forward 1st speed (F1), Reverse 1st speed (R1) and Forward/Reverse 2nd speed (F/R2). Forward and Reverse 2nd speed (F/R2) share the same output relay.



4.2.2.2 Output Relay Actions at 2nd Speed (dual speed model only)

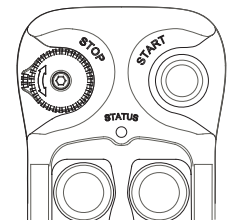
1. **3 output relays configuration with Closed/Closed contact at 2nd speed**

F1 (or R1) output relay closed at 1st speed and F1 + F/R2 (or R1 + F/R2) output relays closed at 2nd speed. **See Section 4.2.3.1 on page 27** on how to set to this function.



4.2.2.3 START + AUX Function

After executing the START function at transmitter startup, the same START button becomes an auxiliary function with momentary contact connected through K10 Function output relay. There are other types of auxiliary functions made available for K10 Function output relays (**see Section 4.2.5 on page 30**). Contact a Magnetek representative if your application requires other types of auxiliary function connected to the Function output relay.



4.2.2.4 ON/OFF Pushbutton Function

The user can set any of the two adjacent pushbuttons on the transmitter to behave like a mechanical ON and OFF rocker or toggle switch. ON output relay closes when ON pushbutton is pressed (OFF output relay opens) and OFF output relay closes when OFF pushbutton is pressed (ON output relay opens). **See Section 4.2.3.1 on page 27** on how to set to this function.

4.2.2.5 Brake Function (dual speed model only)

When the transmitter pushbutton is released from 2nd speed up to 1st speed, both 1st and 2nd speed output relays will open for up to 1 second and then with 1st speed output relay closed thereafter. **See Section 4.2.3.1 on page 27** on how to set to this function.

4.2.2.6 External Warning Function

The user can install an external warning device (rotating lights, horn, etc.) to the K10 Function output relay located inside the receiver. The user can choose which pushbutton pair (or pairs) triggers the external warning device when pressed. **See Section 4.2.3.1 on page 27** on how to set to this function.

4.2.2.7 Momentary Contact

When pushbutton is released, the corresponding output relay will open or deactivate. This type of relay action usually applies to external applications such as horn and buzzer. **See Section 4.2.3.2 on page 28** on how to set to this function.

4.2.2.8 Toggled Contact

When pushbutton is released, the corresponding output relay will maintain contact or closure until next time the user presses the same pushbutton. This type of relay action usually applies to external application such as lights. **See Section 4.2.3.2 on page 28** on how to set to this function.

4.2.2.9 Receiver Channel Scanning Function

- (1) → “00” manufacturer preset (channel X)*
S3 DIP 7~8
- (2) → “01” scans 2 channels (channel X and channel X+1)
S3 DIP 7~8
- (3) → “10” scans 3 channels (channel X... channel X+2)
S3 DIP 7~8
- (4) → “11” scans 4 channels (channel X... channel X+3)**
S3 DIP 7~8

* Channel X → channel set on the Channel dipswitch.

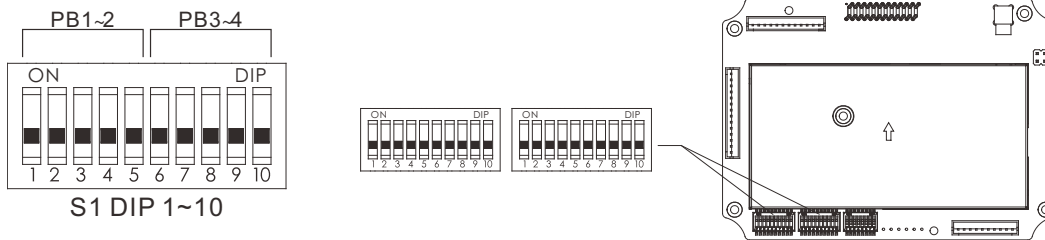
** Contact a Magnetek representative if your application requires scanning more than 4 channels.

Example: If the first 6 dipswitch positions are set to channel 01 (000001), when set to 2-channel scanning (type-2 above) the receiver will only scan channel 01 and 02.

4.2.3 Dipswitch Settings

4.2.3.1 Interlocked Pushbutton Pair

Interlocked means any pushbutton pair cannot be pressed simultaneously as each press will cancel the other out. Interlocked setting usually applies to electric motor's forward and reverse motion and ON and OFF switches. Each dipswitch on the decoder board corresponds to a pushbutton pair.

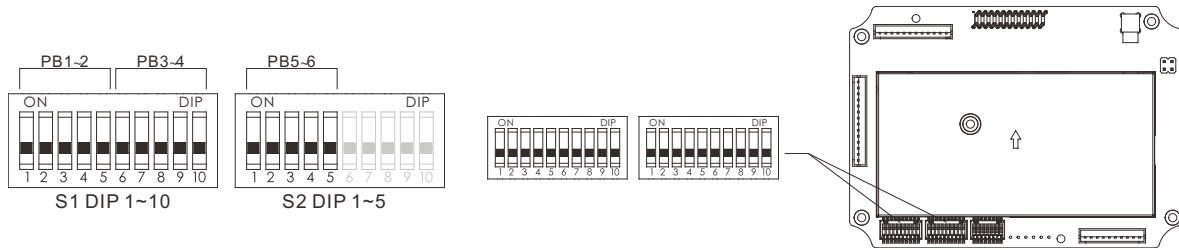


Dip Settings	Function
00000	Single speed only
00001	3 output relays Closed/Closed relay action at 2nd speed (shared 2nd speed output relay)
00010	ON (right button) & OFF (left button)
00100	ON (right button) & OFF (left button) (EMS → all relays deactivate when STOP button is pressed)
00101	On + Start/Off + Start - For added safety, you must first press and hold the START button and then press the ON or OFF pushbutton to activate the output relay.
00110	FWD/REV toggled
00111	FWD/REV toggled (EMS → all relays deactivate when STOP button is pressed)
01000	Single speed + External warning*
01001	3 output relays Closed/Closed relay action + External warning*
01010	3 output relays Closed/Closed relay action + Brake
01011	3 output relays Closed/Closed relay action + Brake + External warning*

* External warning function requires installing an external warning device such as horn or lights to the K10 Function output relay.

4.2.3.2 Non-Interlocked Pushbutton Pair

Non-interlocked setting allows a pushbutton pair to be pressed simultaneously. It usually applies to equipment auxiliary functions such as lights, horn or buzzer. Five dip positions correspond to a pushbutton pair.

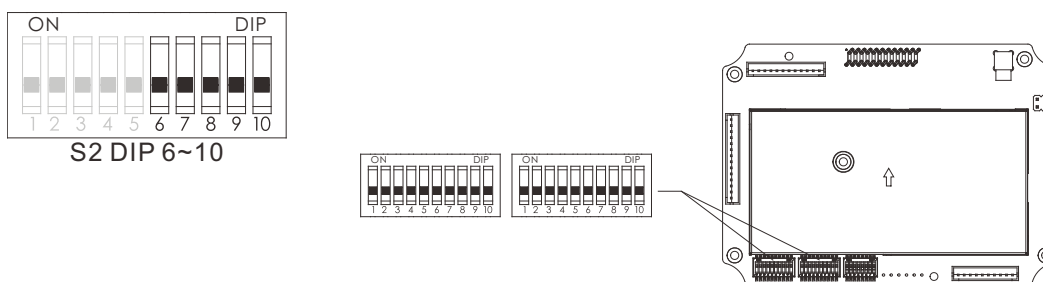


Dip Settings	Left Pushbutton	Right Pushbutton
10000	Normal	Normal
10001	Normal	Toggle
10010	Normal	Toggle (EMS)
10011	Normal	Normal + Start
10100	Toggle	Normal
10101	Toggle	Toggle
10110	Toggle	Toggle (EMS)
10111	Toggle	Normal + Start
11000	Toggle (EMS)	Normal
11001	Toggle (EMS)	Toggle
11010	Toggle (EMS)	Toggle (EMS)
11011	Toggle (EMS)	Normal + Start
11100	Normal + Start	Normal
11101	Normal + Start	Toggle
11110	Normal + Start	Toggle (EMS)
11111	Normal + Start	Normal + Start

* EMS → all relays deactivate when STOP button is pressed.

4.2.4 Other Dipswitch Settings

Jumper setting applies to functions such as the standard or reversed logic A/B selector sequence, firmware version, system testing and remote pairing methods.



S2 Dip Position 6	Function
Dip set to "0" or down	Reserved
Dip set to "1" or up	Reserved
S2 Dip Position 7	Function
Dip set to "0" or down	Normal
Dip set to "1" or up	Pressing the START button is required when receiver MAIN relays are deactivated (cancels ANY button setting in Section 4.1.4 on page 20)
S2 Dip Position 8	Function
Dip set to "0" or down	Normal
Dip set to "1" or up	Display system firmware version
S2 Dip Position 9	Function
Dip set to "0" or down	Normal
Dip set to "1" or up	System testing (receiver MAIN relays disabled)
S2 Dip Position 10	Function
Dip set to "0" or down	Receiver-to-transmitter remote pairing (pressing the Pairing button required)
Dip set to "1" or up	Receiver-to-transmitter remote pairing (pressing the Pairing button not required)

4.2.5 Other Function Output Relays Settings

Listed below are other types of functions that can be outputted through the K10 Function output relay via the infrared IR programmer unit. Contact a Magnetek representative for more details.

LV → Function relay closes when receiver voltage is low.

ID → Function relay works simultaneously with all motion commands.

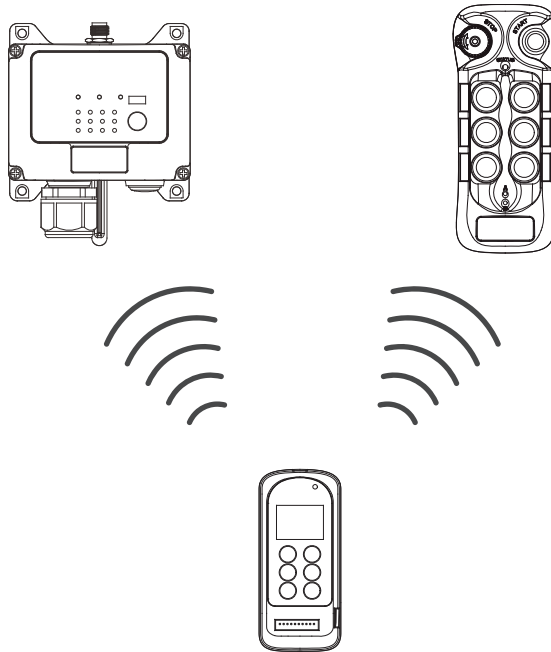
NORMAL → START function + AUX with normal momentary output.

TOGGLE → START function + AUX with toggled/latching output.

TOG&E → START function + AUX with toggled/latching output affected by the STOP command (Function relay opens when STOP button is pressed down).

EXT → Function relay works simultaneously with the receiver MAIN relays.

HORN → Function relay closes for up to 3 seconds when START command is executed at transmitter power on and then becomes a normal momentary output thereafter.



4.2.6 System Channels Table

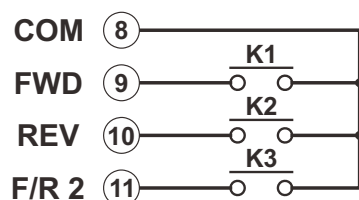
Channel	Dipswitch Setting	Channel	Dipswitch Setting
01	000001	32	100000
02	000010	33	100001
03	000011	34	100010
04	000100	35	100011
05	000101	36	100100
06	000110	37	100101
07	000111	38	100110
08	001000	39	100111
09	001001	40	101000
10	001010	41	101001
11	001011	42	101010
12	001100	43	101011
13	001101	44	101100
14	001110	45	101101
15	001111	46	101110
16	010000	47	101111
17	010001	48	110000
18	010010	49	110001
19	010011	50	110010
20	010100	51	110011
21	010101	52	110100
22	010110	53	110101
23	010111	54	110110
24	011000	55	110111
25	011001	56	111000
26	011010	57	111001
27	011011	58	111010
28	011100	59	111011
29	011101	60	111100
30	011110	61	111101
31	011111	62	111110

5 Receiver Installation

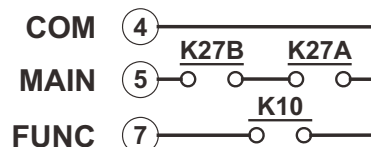
5.1 Output Relay Contact Diagrams

5.1.1 Flex 4BASE-MRX (dual speed model)

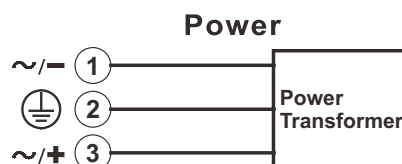
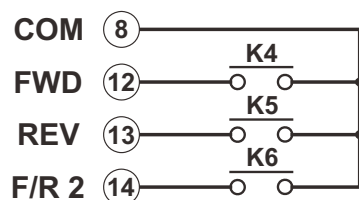
PUSH BUTTON 1-2



MAIN / FUNC

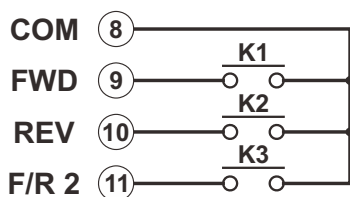


PUSH BUTTON 3-4

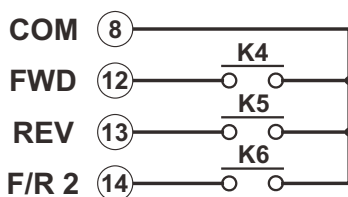


5.1.2 Flex 6BASE-MRX (dual speed model)

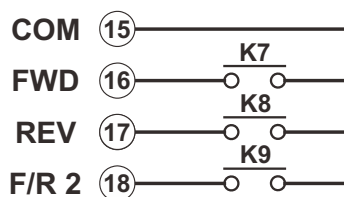
PUSH BUTTON 1-2



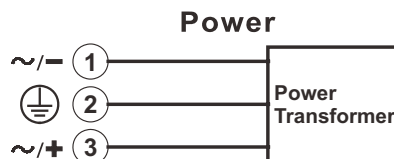
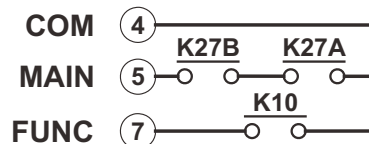
PUSH BUTTON 3-4



PUSH BUTTON 5-6



MAIN / FUNC

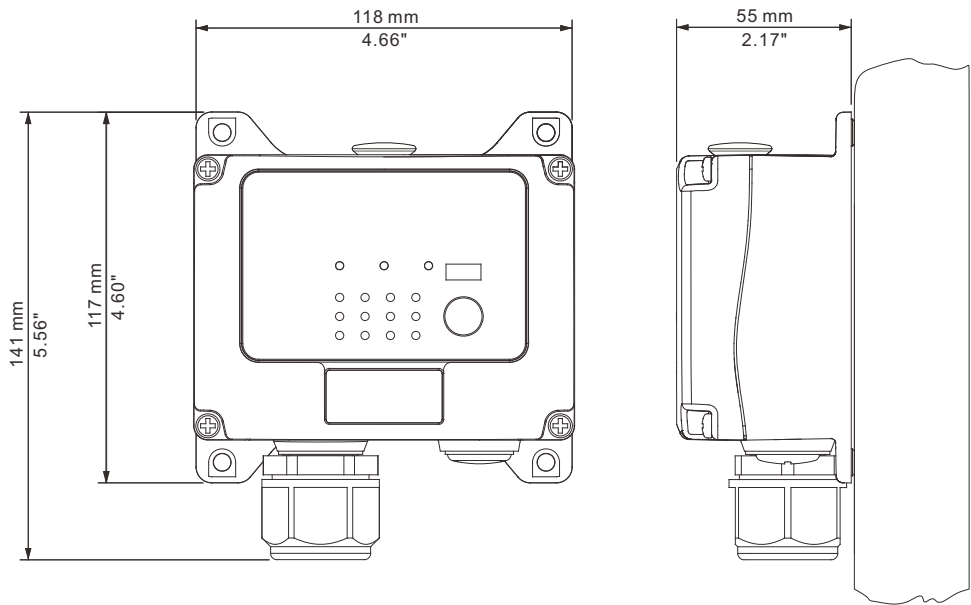


- For 9-36VDC power supply, wire #1 corresponds to the negative charge (-) and wire #3 corresponds to the positive charge (+). Wire #2 is for GROUND.

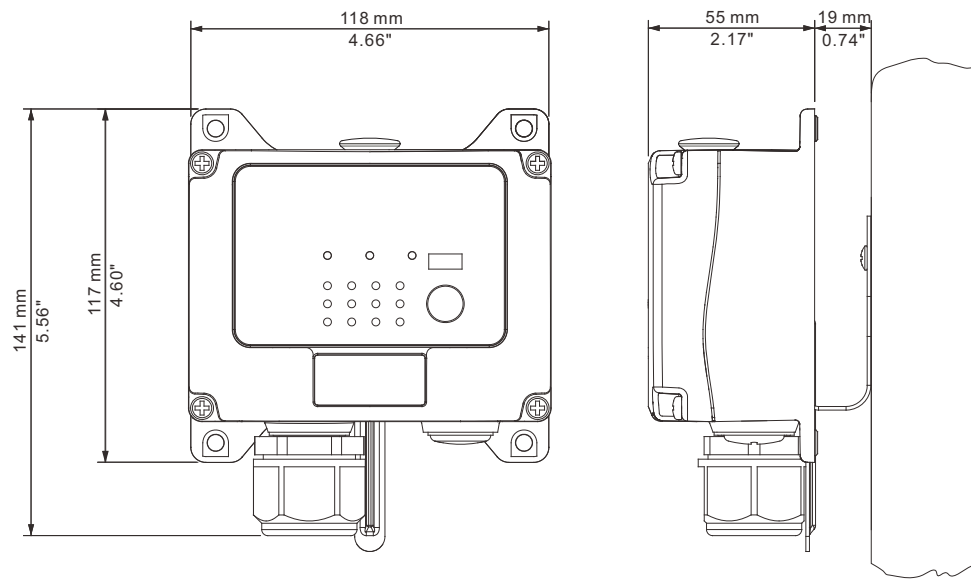
5.2 Pre-installation Precautions

1. Make sure the transmitter and receiver have the same serial numbers and are set to the same channel.
2. Make sure the receiver is not set to the same channel as any other systems in use in the surrounding area.
3. Make sure the crane or equipment is working properly prior to installation.
4. Make sure the power source to the receiver is set correctly.
5. Switch off the main power source to the crane or equipment prior to installation.

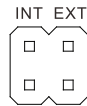
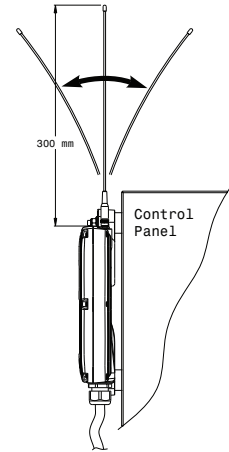
5.3 Step-by-Step Installation



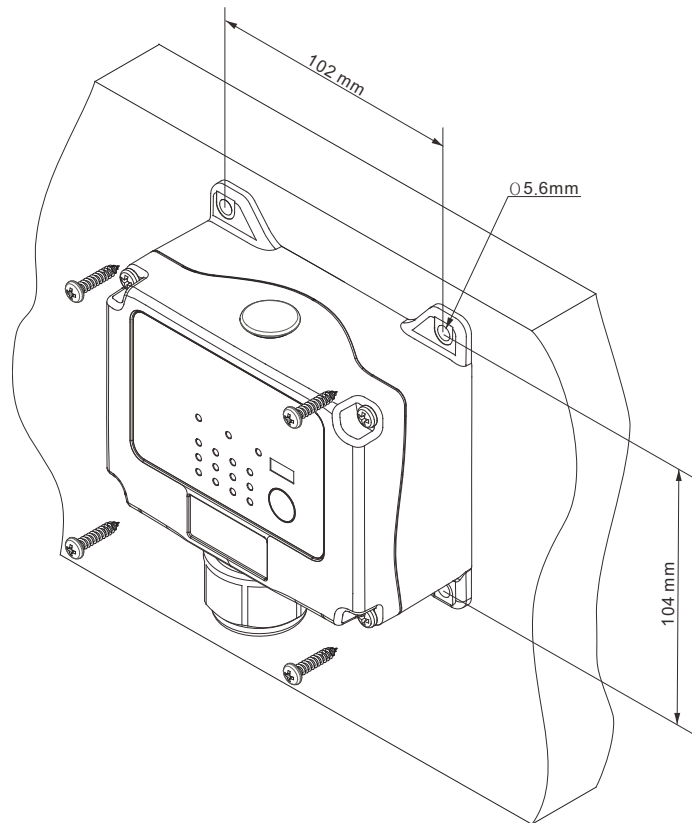
With Optional Removable Mounting Bracket



1. For best reception, the location of the receiver should be visible to the operator at all times.
2. The location selected should not be exposed to high levels of electric noise. Mounting the receiver next to an unshielded variable frequency drive may cause radio interference. Always locate the receiver as far away from variable frequency drive and electric motor as possible.
3. Ensure the selected location has adequate space to accommodate the receiver. If an external antenna is used, to avoid the possibility of antenna damage always locate the receiver where the antenna is free from any obstructions.
4. When installing an external antenna, make sure the MCX jack located on the RF/decoder board inside the receiver is connected and jumper set to "EXT" position.

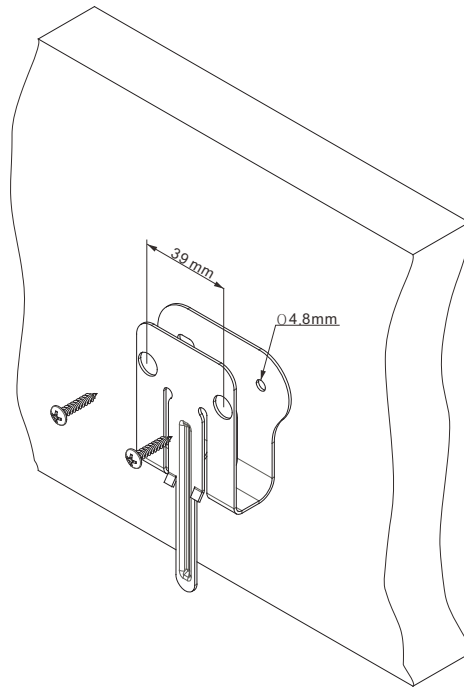


5. For better reception, make sure the receiver is in an upright position.
6. Drill four holes on the control panel, wall or location where the receiver is to be installed.
7. Make sure the screws are tightened after installation (not provided with the system).



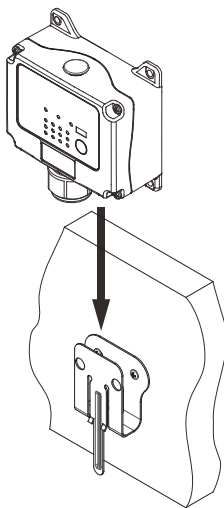
5.3.1 With Optional Removable Mounting Bracket

1. Drill two holes on the control panel, wall or location where the receiver is to be installed.

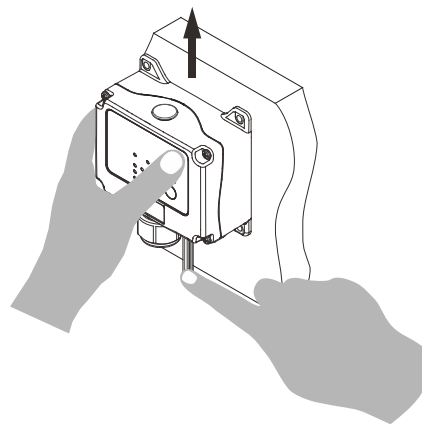


2. Slide the receiver down along the guided track to secure the receiver to the mounting bracket.
3. Remove the receiver by pressing down the bracket release and pull the receiver upward until it clears the guided track.

Install



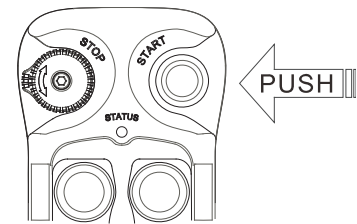
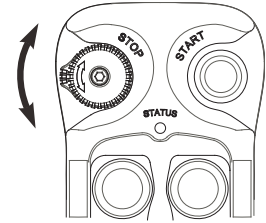
Remove



6 Operating Procedures

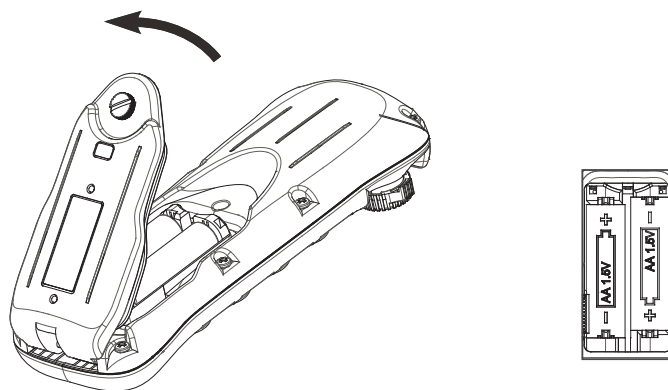
6.1 General Operation

1. Reset the STOP button located on the top left corner of the transmitter by rotating it clockwise or counterclockwise; the button will pop up. Transmitter is powered on when the STOP button is elevated.
2. After turning on the transmitter power, check the Status LED on the transmitter for any sign of system irregularities (*see Section 6.3.1 Transmitter Status Indications on page 39*). If the transmitter is in good working order the Status LED will display solid green for up to 2 seconds at power on (no faults detected).
3. Press the START button for up to 1 second to activate the receiver MAIN relays (Status LED solid green). When the receiver MAIN relays are activated, the Status LED will change from solid green to solid orange (system on). The same START button becomes an auxiliary function thereafter (*see Section 4.2.2.3 START + AUX Function on page 24*). Then press any pushbutton on the transmitter to begin operation. Pressing any pushbutton prior to executing the START command at startup will result in no signals transmitted (Status LED blinks orange).
4. In case of an emergency, press down the STOP button to disconnect the receiver MAIN relays and the transmitter power. To resume operation, rotate the STOP button clockwise or counterclockwise; the button will pop up. Then press the START button for up to 1 second to reconnect the receiver MAIN relays. For safety, pressing the START button is strictly required every time the transmitter is turned on or after every STOP button reset.
5. After 5 minutes of inactivity (pushbutton not pressed), the receiver MAIN relays are temporarily disconnected (*see Section 4.1.5 Transmitter Inactivity Timer Settings on page 21*). Press any pushbutton or the START button to resume operation (*see Section 4.1.4 Transmitter Start Function Settings on page 20*). The receiver MAIN relays are also temporarily disconnected when the system encounters strong radio interference, dead spots, low battery condition, and system out of operating range.
6. Turn off the transmitter power by pressing down the STOP button. It will disconnect the transmitter power and the receiver MAIN relays altogether.



6.2 Changing Batteries

Changing transmitter batteries (“AA” alkaline battery x 2) by unscrewing the battery cover located on the backside of the transmitter. During battery installation make sure the batteries are installed correctly, with “+” to “+” charge and “-” to “-” charge. Also make sure the screw is tightened after battery installation to avoid water, moisture, dirt, grease, and other liquid penetration. ***Refer to the charging station instruction manual if this system is equipped with one.***



6.3 System Status Light Indications

6.3.1 Transmitter Status Indications

Type	Display Type	Indication
1	Solid red	Voltage below 1.8V at initial power on or during operation
2	Solid red → off	Voltage below 1.75V during operation (receiver MAIN relays shut off)
3	1 red blink followed by a 2-second pause	Voltage below 1.85V during operation (changing batteries is recommended)
4A	2 red blinks followed by a 2-second pause	Defective or jammed pushbutton detected at initial power on
4B	No light displayed	When defective pushbutton condition occurs (2 red blinks, type 4A above), find out which pushbutton is defective by pressing all of them one at a time. If the pushbutton is in good working order when pressed, the Status LED is off. If the Status LED maintains 2 red blinks then the pushbutton is defective.
5	4 red blinks followed by a 2-second pause	Transmitter is unable to lock onto the assigned channel
6	Solid green for up to 2 seconds	Transmitter power on with no faults detected
7	Blinking green	Transmission in progress
8	Blinking orange	Pressing any pushbutton prior to executing the START command at power on
9	2 orange blinks followed by a 2-second pause	Receiver MAIN relays jammed or defective
10	3 orange blinks followed by a 2-second pause	Decoding processors defective
11	Solid orange when the START button is pressed and held at initial system startup	Receiver MAIN relays activated

6.3.2 Receiver Status Indications

Type	Display Type (Green & Red)	Indication
1	Fast green blinks	Decoding in process
2	Slow green blinks	Decoding on standby
3	2 red blinks	Receiver MAIN relays jammed or defective
4	3 red blinks	Decoding processors defective
5	4 red blinks	Receiving RF defective
6	Fast red blinks	Incorrect transmitter serial number
7	Solid red	Receiver low voltage
8	No light displayed	Decoding processors defective

6.3.3 Receiver Power Indications

Type	Display Type (Red)	Indication
1	On	Power to receiver
2	Off	No power to receiver

6.3.4 Receiver COM Indications

Type	Display Type (Red)	Indication
1	On	Power to relay board
2	Off	No power to relay board

7 General Specifications

Frequency Range:	433.050 MHz - 434.575 MHz
Number of Channels:	62 channels
Channel Spacing:	25 KHz
Modulation:	Digital Frequency Modulation based on Manchester Code, 20-bit address, 32-bit CRC and Hamming Code.
Encoder & Decoder:	Microprocessor-controlled
Transmitting Range:	>100 meters (300 feet)
Hamming Distance:	>6
Frequency Control:	Synthesized PLL
Receiver Type:	Frequency Auto Scanning
Receiver Sensitivity:	-116 dBm
Spurious Emission:	-50 dB
Antenna Impedance:	50 ohms
Responding Time:	40 mS (average)
Transmitting Power:	2.0 mW
Enclosure Type:	NEMA4
Enclosure Rating:	IP66
Output Contact Rating:	250V @ 6 Amps
Transmitter Operating Voltage:	3.0VDC
Receiver Power Consumption:	7VA (max)
Available Receiver Voltages:	9 - 36VDC 24 - 48VAC 48 - 240VAC
Operating Temperature:	-25°C - 75°C / -13°F - 167°F
Transmitter Dimension:	4BASE: 141 mm (L) x 69 mm (W) x 38 mm (H) 6BASE: 164 mm (L) x 69 mm (W) x 38 mm (H)
Receiver Dimension:	120 mm (L) x 90 mm (W) x 55 mm (H)
Transmitter Weight:	4BASE: 203 g / 7.2 oz (including batteries) 6BASE: 226 g / 8.0 oz (including batteries)
Receiver Weight:	900 kg / 2.0 lb (including output cable)

8 Declaration of Conformity

For the following equipment:

Product	:	<u>Flex ECO (BASE) Series Radio Remote Control System</u>
Multiple Listee Model No.	:	<u>Flex ECO (BASE) 4S/4X, 6S/6X, 8S/8X and 12S/12X</u>
Manufacturer's Name	:	<u>Advanced Radiotech Corporation</u>
Manufacturer's Address	:	<u>1F, 288-1, Hsin Ya Road, Chien Chen District,</u> <u>Kaohsiung, Taiwan</u>

We hereby declare, that all major safety requirements, concerning the CE Mark Directive 2006/42/EC and Low Voltage Directive 2006/95/EC, Electromagnetic Compatibility Directives 2004/108/EC, R&TTE Directive 1999/5/EC are fulfilled, as laid out in the guideline set down by the member states of the EEC Commission.

The standards relevant for the evaluation of the electrical safety requirements are as follows:

EMC	:	<u>EN 301 489-1 V1.9.2 + EN 301 489-3 V1.6.1</u>
R&TTE	:	<u>EN 300 220-1 V2.4.1 + EN 300 220-2 V2.4.1</u>
SAFETY	:	<u>EN 60950:2006+A1+A11+A12</u>
MACHINERY	:	<u>EN 60204-32:2008, EN ISO 13849-1:2008 (PLd)</u>
	:	<u>EN 13557:2003+A2:2008</u>
OTHERS	:	<u>EN 60529 (IP66)</u>

Test reports issued by:

EMC	:	<u>SGS</u>
R&TTE	:	<u>SGS</u>
SAFETY	:	<u>SGS</u>
MACHINERY	:	<u>SGS</u>
OTHERS	:	<u>SGS</u>

Person responsible for making this declaration:



Tom Jou / President

Name and signature of authorized person