

## Flex 6Base® Radio Control Equipment Instruction Manual



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## Your New Radio Remote Control System

Thank you for your purchase of Magnetek's Flex Base® Radio Remote Equipment Control. Magnetek has set a completely new standard in radio-remote performance, dependability, and value with this unique new line of handheld transmitters.

If your product ever needs modification or service, please contact one of our representatives at the following locations:

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#### PRODUCT MANUAL SAFETY INFORMATION

Magnetek, Inc. (Magnetek) offers a broad range of radio remote control products, control products and adjustable frequency drives, and industrial braking systems for overhead material handling applications. This manual has been prepared by Magnetek to provide information and recommendations for the installation, use, operation and service of Magnetek's material handling products and systems (Magnetek Products). Anyone who uses, operates, maintains, services, installs or owns Magnetek Products should know, understand and follow the instructions and safety recommendations in this manual for Magnetek Products.

The recommendations in this manual do not take precedence over any of the following requirements relating to cranes, hoists and lifting devices:

- Instructions, manuals, and safety warnings of the manufacturers of the equipment where the radio system is used,
- Plant safety rules and procedures of the employers and the owners of facilities where the Magnetek Products are being used,
- Regulations issued by the Occupational Health and Safety Administration (OSHA),
- Applicable local, state or federal codes, ordinances, standards and requirements, or
- Safety standards and practices for the overhead material handling industry.

This manual does not include or address the specific instructions and safety warnings of these manufacturers or any of the other requirements listed above. It is the responsibility of the owners, users and operators of the Magnetek Products to know, understand and follow all of these requirements. It is the responsibility of the owner of the Magnetek Products to make its employees aware of all of the above listed requirements and to make certain that all operators are properly trained. No one should use Magnetek Products prior to becoming familiar with and being trained in these requirements.

#### WARRANTY INFORMATION

FOR INFORMATION ON MAGNETEK'S PRODUCT WARRANTIES BY PRODUCT TYPE, PLEASE VISIT WWW.MAGNETEK.COM.

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## **1** Introduction

The **Flex Base**® radio remote control systems are designed for control of industrial equipment and machinery such as overhead traveling cranes, jib cranes, gantry cranes, tower cranes, electric hoists, winches, monorails, conveyor belts, mining equipment, and all other material handling equipment where wireless control is preferred.

Each **Flex Base** system consists of a transmitter handset and a receiver unit. Other standard-equipped accessories include transmitter lanyard, vinyl pouch, pushbutton labels, output cable, and instruction manual CD.

List of notable features include:

- 62 user-programmable channels advanced synthesized RF controls with 62 built-in programmable channels set via pushbuttons and dipswitches.
- Wireless remote pairing function system pairing and cloning can be done easily and wirelessly.
- Over one million unique address codes (20bit) each Flex Base system has its own address code and serial number, and never repeats.
- Advanced controls the Flex Base system utilizes dual advanced microprocessor controls with 32bit CRC and Hamming Code, which provide ultra-fast, safe, precise, and error-free encoding and decoding.
- Two-way transmission transmitter and receiver communicate with one another for safe, precise and uninterrupted operation.
- Reliable pushbuttons the pushbuttons are rated for more than one million press cycles.
- Low power consumption requires only two "AA" Alkaline batteries for more than 150 hours of uninterrupted operation between replacements.
- Ultra-durable nylon and fiberglass composite enclosures highly resistant to breakage and deformation even in the most abusive environments. The receiver enclosures and output cables are UL94-V0 rated.
- Fully sealed enclosures the transmitter and receiver enclosures are IP66 rated.
- Full compliance all systems are fully complied with the FCC Part-15 Rules and European Safety Standards.
- Other optional accessories and features include transmitter magnet mount, transmitter waist belt, 2 and 3 position rotary switches, transmitter rubber guards, miniature indicator lights and buzzer, dual-crane tandem function, multi-crane random access function, and many others.

## **2 Radio Controlled Safety**

#### WARNINGS and CAUTIONS

Throughout this document, WARNING and CAUTION statements have been deliberately placed to highlight items critical to the protection of personnel and equipment.

WARNING – A warning highlights an essential operating or maintenance procedure, practice, etc. which, if not strictly observed, could result in injury or death of personnel, or long term physical hazards. Warnings are highlighted as shown below:



CAUTION – A caution highlights an essential operating or maintenance procedure, practice, etc. which if not strictly observed, could result in damage to, or destruction of equipment, or loss of functional effectiveness. Cautions are highlighted as shown below:



#### WARNINGS and CAUTIONS SHOULD NEVER BE DISREGARDED.

The safety rules in this section are not intended to replace any rules or regulations of any applicable local, state, or federal governing organizations. Always follow your local lockout and tagout procedure when maintaining any radio equipment. The following information is intended to be used in conjunction with other rules or regulations already in existence. It is important to read all of the safety information contained in this section before installing or operating the Radio Control System.

## 2.1 Critical Installation Considerations



PRIOR TO INSTALLATION AND OPERATION OF THIS EQUIPMENT, READ AND DEVELOP AN UNDERSTANDING OF THE CONTENTS OF THIS MANUAL AND THE OPERATION MANUAL OF THE EQUIPMENT OR DEVICE TO WHICH THIS EQUIPMENT WILL BE INTERFACED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

FOLLOW YOUR LOCAL LOCKOUT TAGOUT PROCEDURE BEFORE MAINTAINING ANY REMOTE CONTROLLED EQUIPMENT. ALWAYS REMOVE ALL ELECTRICAL POWER FROM THE EQUIPMENT BEFORE ATTEMPTING ANY INSTALLATION PROCEDURES. DE-ENERGIZE AND TAGOUT ALL SOURCES OF ELECTRICAL POWER BEFORE TOUCH-TESTING ANY EQUIPMENT. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

AFTER INSTALLATION BE SURE TO VERIFY THAT THE TRANSMITTER IS NOT INTERFERING WITH OTHER EQUIPMENT IN THE AREA. ALSO VERIFY THAT OTHER EQUIPMENT IS NOT INTERFERING WITH THE TRANSMITTER AND ITS ASSOCIATED EQUIPMENT. FAILURE TO FOLLOW THESE WARNINGS COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

## 2.2 General

Radio controlled equipment operates in several directions. Quite frequently, the equipment is operated in areas where people are working in close proximity to the equipment. **The operator must exercise extreme caution at all times.** Workers must constantly be alert to avoid accidents. The following recommendations have been included to indicate how careful and thoughtful actions may prevent injuries, damage to equipment, or even save a life.

# 2.3 Persons Authorized to Operate Radio Controlled Cranes

Only properly trained persons designated by management should be permitted to operate radio-controlled equipment.

Radio controlled equipment should not be operated by any person who cannot read or understand signs, notices and operating instructions that pertain to the equipment.

Radio controlled equipment should not be operated by any person with insufficient eyesight or hearing or by any person who may be suffering from a disorder or illness, is taking any medication that may cause loss of equipment control, or is under the influence of alcohol or drugs.

# 2.4 Safety Information and Recommended Training for Radio Controlled Equipment Operators

Anyone being trained to operate radio-controlled equipment should possess as a minimum the following knowledge and skills before using the radio-controlled equipment.

#### The operator should:

- have knowledge of hazards pertaining to equipment operation
- have knowledge of safety rules for radio controlled equipment
- have the ability to judge distance of moving objects
- know how to properly test prior to operation
- be trained in the safe operation of the radio transmitter as it pertains to the equipment being operated
- have knowledge of the use of equipment warning lights and alarms
- have knowledge of the proper storage space for a radio control transmitter when not in use
- be trained in transferring a radio control transmitter to another person
- be trained how and when to report unsafe or unusual operating conditions
- test the transmitter emergency stop and all warning devices prior to operation; testing should be done on each shift, without a load
- be thoroughly trained and knowledgeable in proper and safe operation of the equipment that utilizes the radio control
- know how to keep the operator and other people clear of hazardous areas
- know and follow the local lockout and tagout procedures when servicing radio controlled equipment
- know and follow all applicable operating and maintenance manuals, safety procedures, regulatory requirements, and industry standards and codes

#### The operator shall not:

- operate the equipment if the direction of travel or function engaged does not agree with what is indicated on the controller
- operate any damaged or malfunctioning equipment
- change any settings or controls without authorization and proper training
- · remove or obscure any warning or safety labels or tags
- leave power on the radio controlled equipment when the equipment is not in operation
- operate any equipment using a damaged controller because the unit may be unsafe
- operate manual motions with other than manual power
- operate radio controlled equipment when low battery indicator is on



THE OPERATOR SHOULD NOT ATTEMPT TO REPAIR ANY RADIO CONTROLLER. IF ANY PRODUCT PERFORMANCE OR SAFETY CONCERNS ARE OBSERVED, THE EQUIPMENT SHOULD IMMEDIATELY BE TAKEN OUT OF SERVICE AND BE REPORTED TO THE SUPERVISOR. DAMAGED AND INOPERABLE RADIO CONTROLLER EQUIPMENT SHOULD BE RETURNED TO MAGNETEK FOR EVALUATION AND REPAIR. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

## 2.5 Transmitter Unit

Transmitter switches should never be mechanically blocked ON or OFF. When not in use, the operator should turn the transmitter OFF. A secure storage space should be provided for the transmitter unit, and the transmitter unit should always be placed there when not in use. This precaution will help prevent unauthorized people from operating the material handling equipment.

Spare transmitters should be stored in a secure storage space and only removed from the storage space after the current transmitter in use has been turned OFF, taken out of the service area and secured.

## 2.6 Pre-Operation Test

At the start of each work shift, or when a new operator takes control of the equipment, operators should do, as a minimum, the following steps before making lifts with any equipment:

Test all warning devices.

Test all functions.

Test the transmitter machine stop.

## 2.7 Handling Batteries



KNOW AND FOLLOW PROPER BATTERY HANDLING, CHARGING AND DISPOSAL PROCEDURES. IMPROPER BATTERY PROCEDURES CAN CAUSE BATTERIES TO EXPLODE OR DO OTHER SERIOUS DAMAGE. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

Use only batteries approved by Magnetek for the specific product.

Do not dispose of a battery pack in fire; it may explode.

Do not attempt to open the battery pack.

Do not short circuit the battery.

Keep the battery pack environment cool during storage (i.e., not in direct sunlight or close to a heating source).

## 2.8 Optional Rechargeable Battery Charging

For those transmitters equipped with rechargeable batteries and battery chargers, all users shall be familiar with the instructions of the charger before attempting to use.

Do not attempt to charge non-rechargeable battery packs in the charger.

Avoid charging partially discharged rechargeable batteries to help prolong battery cycle life.

Do not charge batteries in a hazardous environment.

Keep the battery pack environment cool during charging (i.e., not in direct sunlight or close to a heating source).

Do not short the charger.

Do not attempt to charge a damaged battery.

Use only Magnetek approved chargers for the appropriate battery pack.

Do not attempt to use a battery that is leaking, swollen or corroded.

Charger units are not intended for outdoor use. Only use charger units indoors.

## 2.9 Battery Disposal

Before disposing of batteries consult local and governmental regulatory requirements for proper disposal procedure.

## 2.10 Crane/Lifting Device Specific Warnings



ALL EQUIPMENT MUST HAVE A MAINLINE CONTACTOR INSTALLED AND ALL TRACKED CRANES, HOISTS, LIFTING DEVICES AND SIMILAR EQUIPMENT MUST HAVE A BRAKE INSTALLED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

AN AUDIBLE AND/OR VISUAL WARNING MEANS MUST BE PROVIDED ON ALL REMOTE CONTROLLED EQUIPMENT AS REQUIRED BY CODE, REGULATION, OR INDUSTRY STANDARD. THESE AUDIBLE AND/OR VISUAL WARNING DEVICES MUST MEET ALL GOVERNMENTAL REQUIREMENTS. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

THE DIRECT OUTPUTS OF THIS PRODUCT ARE NOT DESIGNED TO INTERFACE DIRECTLY TO TWO STATE SAFETY CRITICAL MAINTAINED FUNCTIONS, I.E., MAGNETS, VACUUM LIFTS, PUMPS, EMERGENCY EQUIPMENT, ETC. A MECHANICALLY LOCKING INTERMEDIATE RELAY SYSTEM WITH SEPARATE POWER CONSIDERATIONS MUST BE PROVIDED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH OR DAMAGE TO EQUIPMENT.

Cranes, hoists, lifting devices and other material handling equipment can be large, and operate at high speeds.

#### The operator should:

- continuously watch and monitor status of lifted loads
- know and follow cable and hook inspection procedures

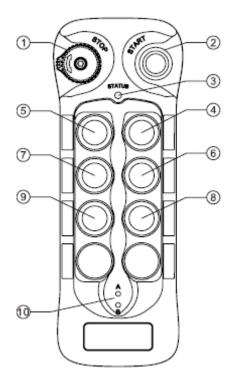
#### The operator shall not:

- lift or move more than the rated load
- use the crane, hoist or lifting device to lift, support or transport people
- lift or carry any loads over people
- operate the crane, hoist or lifting device unless all persons, including the operator, are and remain clear of the supported load and any potential pinch points
- operate a crane, hoist or lifting device when the device is not centered over the load
- operate a crane, hoist or lifting device if the chain or wire rope is not seated properly in the sprockets, drum or sheave
- leave any load unattended while lifted

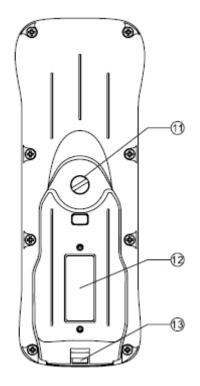
## **3 General System Information**

## 3.1 Transmitter

### 3.1.1 External Illustration

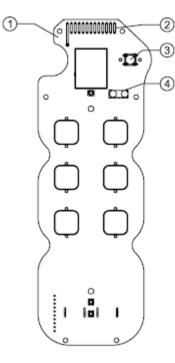


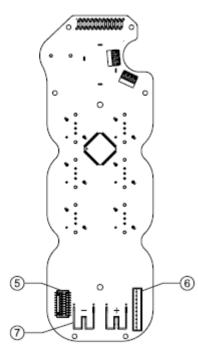
- 1. STOP Button
- 2. START Button
- 3. Status LED Indicator
- 4. Pushbutton 1 (PB1)
- 5. Pushbutton 2 (PB2)
- 6. Pushbutton 3 (PB3)
- 7. Pushbutton 4 (PB4)



- 8. Pushbutton 5 (PB5)
- 9. Pushbutton 6 (PB6)
- 10. A/B LED Indicators
- 11. Battery Cover Screw
- 12. System Information
- 13. Lanyard and Waist Belt Attachment Slot

### 3.1.2 Internal Illustration

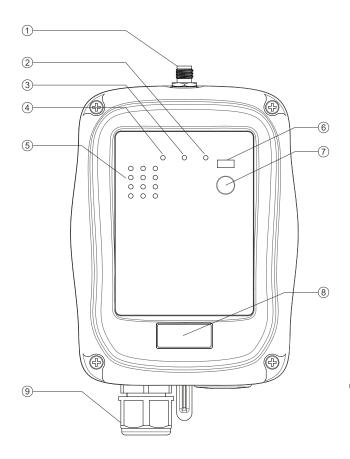




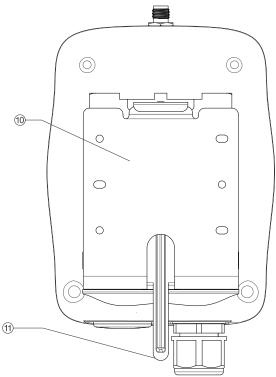
- 1. RF/Encoder Board
- 2. Antenna
- 3. START Button
- 4. Infrared Sensors

- 5. Function Dipswitch
- 6. Programming Port
- 7. Battery Contacts

## 3.2 Receiver 3.2.1 External Illustration

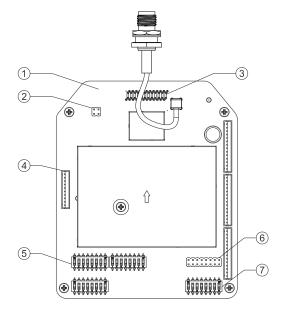


- 1. External Antenna Port (optional)
- 2. COM LED Indicator
- 3. Status LED Indicator
- 4. Power LED Indicator
- 5. Output Relay LED Indicators
- 6. Infrared Sensors

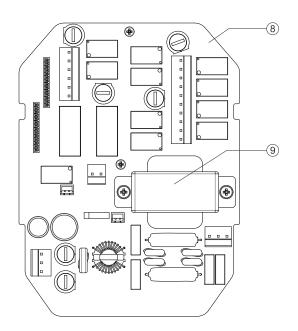


- 7. Remote Pairing Button
- 8. System Information
- 9. Cord Grip
- 10. Mounting Bracket
- 11. Mounting Bracket Release

### 3.2.2 Internal Illustration



- 1. RF/Decoder Board
- 2. INT/EXT Antenna Jumpers
- 3. Internal Antenna
- 4. Programming Port
- 5. Function Dipswitches



- 6. Function Jumpers
- 7. Channel Dipswitch
- 8. AC Line Filter/Relay Board
- 9. Power Transformer

## **4** Function Settings

## 4.1 Transmitter

## 4.1.1 Transmitter Firmware Version

- 1. Press down the STOP button (transmitter power off).
- 2. Press and hold PB1 and PB3 at the same time.
- 3. Reset the STOP button by rotating it clockwise or counterclockwise; it will pop up (transmitter power on).
- Release PB1 and PB3 at the same time. The Status LED will display the firmware version with red, green and orange blinks. Exit Firmware Version mode by pressing down the STOP button (transmitter power off).

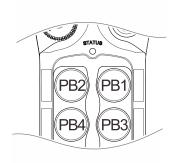
## 4.1.2 Transmitter Channel Settings

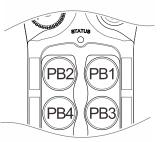
- 1. Press down the STOP button (transmitter power off).
- 2. Press and hold PB1 and PB2 at the same time.
- 3. Reset the STOP button by rotating it clockwise or counterclockwise; it will pop up (transmitter power on).
- Release PB1 and PB2 at the same time. The Status LED displays current channel setting with red and green blinks. A green blink represents the tens (+10) and a red blink represents the units (+1). For example, 1 green blink followed by 5 red blinks is channel 15.
- Change the transmitter channel by pressing PB1 to increment the units (+1) and PB2 to increment the tens (+10). For example, pressing PB2 two times and then PB1 four times is channel 24 (Status LED blinks 2 greens and 4 reds).
- 6. Transfer the newly selected channel to the receiver by pressing and holding the START button until the Status LED turns to constant green (transfer complete). Press down the STOP button if constant green is not shown on the Status LED after more than 10 seconds (transfer incomplete); the transmitter will revert to its previous channel setting. Make sure the receiver power is turned on and within the operating distance during the entire process. Skip step 6 if changing the receiver channel is not required.
- 7. Exit Channel Setting mode by pressing down the STOP button (transmitter power off).

NOTE: When selecting a new channel, make sure each button press does not exceed 3 seconds.

#### Important Note:

Step 6 illustrated above is strictly required if you are intending to change the entire system channel (both transmitter and receiver). The entire system no longer works if step 6 is skipped because the transmitter and receiver channels are now different (new vs. old). In this case, you would have to redo steps 1 through 4 and step 6 to transfer the newly selected transmitter channel to the receiver.

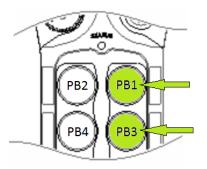




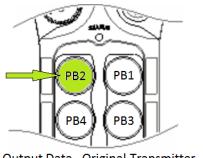
### 4.1.3 Remote Pairing

#### 4.1.3.1 Transmitter-to-Transmitter Pairing

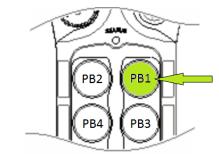
- 1. Obtain the original transmitter.
- 2. Press down the STOP button (transmitter power off).
- 3. Press and hold PB1 and PB3 at the same time.



- 4. Reset the STOP button by rotating it clockwise or counter-clockwise; it will pop up (transmitter power on) after a brief pause, let go of PB1 and PB3.
- 5. Repeat steps 2 through 4 for the new transmitter.
- 6. Now both the original transmitter and the new transmitter are in Remote Pairing Mode.
- 7. Simultaneously press and hold PB2 on the original transmitter (Status LED off and LED-B constant red) and PB1 on the new transmitter (Status LED blinks green and LED-A constant red).



Output Data - Original Transmitter (Press and Hold PB2)

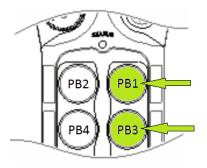


Receiving Data - New Transmitter (Press and Hold PB1)

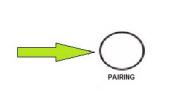
- 8. When the Status LED (receiving data end) turns to constant green while both pushbuttons are still pressed down the pairing is completed.
- 9. Exit Remote Pairing mode by pressing down the STOP button on both transmitters.
- NOTE: During remote pairing make sure the distance between the two transmitters is within 1 meter.

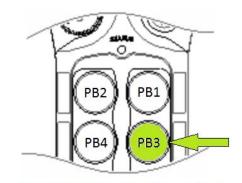
#### 4.1.3.2 Receiver-to-Transmitter Pairing

- 1. Obtain the new transmitter.
- 2. Press down the STOP button (transmitter power off).
- 3. Press and hold PB1 and PB3 at the same time.



- 4. Reset the STOP button by rotating it clockwise or counter-clockwise; it will pop up (transmitter power on) after a brief pause, let go of PB1 and PB3.
- 5. Now the new transmitter is in Remote Pairing mode.
- 6. Ensure power is applied to the Receiver.
- 7. Press and hold both the PAIRING button located on the receiver cover and PB3 on the new transmitter at the same time. When the transmitter Status LED turns to constant green while both pushbuttons are still pressed down the pairing is completed.





Output Data - Receiver (Press and Hold Pairing Button)

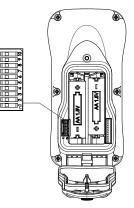
Receiving Data - New Transmitter (Press and Hold PB3)

- 8. Exit Remote Pairing mode by pressing down the STOP button (transmitter power off).
- NOTE: Make sure the pairing process is executed within distance of 10 meters from one another and no other active receivers nearby. During the pairing process, the receiver MAIN relays must be deactivated (relay open).

## 4.1.4 Transmitter Start Function Settings

When the transmitter goes into sleep mode the system is temporarily deactivated (MAIN relays opened). Press the START button or any pushbutton to wake up the system (MAIN relays closed).

	Dipswitch Settings	Function
1	xxxxxxxx <b>0</b>	START Reactivation
2	xxxxxxxxx1	Any Button Reactivation



## 4.1.5 Transmitter Inactivity Timer Settings

Set how long the transmitter enters the sleep mode when not in use (pushbutton not pressed). When the transmitter goes into sleep mode the receiver MAIN relays are deactivated.

	Dipswitch Settings	Time		Dipswitch Settings	Time	
1	xxx <b>000</b> xxxx	1 minute	5	xxx <b>100</b> xxxx	10 minutes	
2	xxx <b>001</b> xxxx	20 seconds	6	xxx101xxxx	30 minutes	
3	xxx <b>010</b> xxxx	3 minutes	7	xxx <b>110</b> xxxx	60 minutes	
4	xxx <b>011</b> xxxx	5 minutes	8	xxx <b>111</b> xxxx	Constant On (sleep mode disabled)	

## 4.1.6 Transmitter Output Power Settings

1mW offers the shortest operating range with lowest battery consumption while 10mW offers the longest operating range with highest battery consumption (manufacture preset at 5mW).

	Dipswitch Settings	Output Power		Dipswitch Settings	Output Power
1	<b>000</b> xxxxxxx	1mW	5	<b>100</b> xxxxxxx	5mW
2	<b>001</b> xxxxxxx	2mW	6	<b>101</b> xxxxxxx	6mW
3	<b>010</b> xxxxxx	3mW	7	<b>110</b> xxxxxxx	8mW
4	<b>011</b> xxxxxxx	4mW	8	<b>111</b> xxxxxxx	10mW

## 2. Press and hold PB3 and PB4 at the same time.

- 3. Reset the STOP button by rotating it clockwise or counter-clockwise; it will pop up (transmitter power on).
- Release PB3 and PB4 at the same time (entered Pushbutton Function mode).
- The Status LED displays current pushbutton function setting with orange, green and red blinks. An orange blink represents the hundreds (+100), a green blink represents the tens (+010), and a red blink represents the units (+001). For example, 1 orange blink followed by 2 green blinks and 5 red blinks is pushbutton function number 125. Pushbutton function number with "0" is represented by no orange, green or red blink. For example, 1 orange blink followed by **5** red blinks is pushbutton function number **105**.
- 6. Set the pushbutton function number by pressing PB3 to increment the hundreds (+100), PB2 to increment the tens (+010), PB1 to increment the units (+001), and PB4 to reset (000 constant orange). For example, pressing PB3 one time, PB2 four times, and PB1 six times is pushbutton function number 146 (Status LED blinks 1 orange, 4 greens and 6 reds).
- 7. Exit Pushbutton Function mode by pressing down the STOP button (transmitter power off).

#### 4.1.8.1 Toggled Pushbutton with LED Indication

Set pushbutton toggled function (latching output relay) with LED indications, LED A and LED B shown inside the shaded box illustrates which LED on the transmitter lights up when the designated pushbutton is pressed.

Function Number	Display Type	PB1	PB2	PB3	PB4	PB5	PB6
1	1 Red	LED A	Normal	Normal	Normal	Normal	Normal
2	2 Reds	Normal	LED B	Normal	Normal	Normal	Normal
3	3 Reds	Normal	Normal	LED A	Normal	Normal	Normal
4	4 Reds	Normal	Normal	Normal	LED B	Normal	Normal
5	5 Reds	Normal	Normal	Normal	Normal	LED A	Normal
6	6 Reds	Normal	Normal	Normal	Normal	Normal	LED B
13	1 Green + 3 Reds	LED A	LED B	Normal	Normal	Normal	Normal
14	1 Green + 4 Reds	Normal	Normal	LED A	LED B	Normal	Normal
15	<b>15</b> 1 Green + 5 Reds		Normal	Normal	Normal	LED A	LED B

<sup>∗</sup> PB1...PB6 → Pushbutton number.

\* Normal  $\rightarrow$  Normal momentary contact.

\* A/1&2 ~ D/1&2  $\rightarrow$  A/B pushbutton select function with designated LED indication.

Other custom functions and settings not listed in this manual can be programmed via the infrared IR programmer unit, such as the system serial number, frequency range, new and updated functions, plus many others. Please contact a Magnetek representative for more details.

4.1.8 Pushbutton Function Settings

1. Press down the STOP button (transmitter power off).





## 4.1.8.2 A/B Pushbutton Select with LED Indication – Standard Right/Left Pushbutton Configuration

There are four different types of A/B selector sequences available. Choose one that is most suitable for your application. Refer to Section 6.1: Output Relay Contact Diagrams.

Type-A selector sequence:  $A \rightarrow B$ 

Type-B selector sequence: Off  $\rightarrow A \rightarrow B$ 

Type-C selector sequence:  $A \rightarrow B \rightarrow A+B$ 

Type-D selector sequence: Off  $\rightarrow A \rightarrow B \rightarrow A+B$ 



Function Number	Display Type	PB1	PB2	PB3	PB4	PB5	PB6
25	5 Greens + 3 Reds	Normal	Normal	Normal	Normal	Normal	A/1&2
26	<b>26</b> 5 Greens + 4 Reds		Normal	Normal	Normal	Normal	B/1&2
27	5 Greens + 5 Reds	Normal	Normal	Normal	Normal	Normal	C/1&2
28	5 Greens + 6 Reds	Normal	Normal	Normal	Normal	Normal	D/1&2

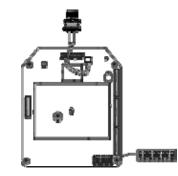
\* PB1...PB6  $\rightarrow$  Pushbutton number.

\* Normal  $\rightarrow$  Normal momentary contact.

\* A/1&2 ~ D/1&2  $\rightarrow$  A/B pushbutton select function with designated LED indication.

## 4.2 Receiver

### 4.2.1 Receiver Channel Settings



Set the receiver channel by configuring the channel dipswitch located on the RF/decoder board, only the first six dip positions are used for channel programming. The system channels table on Section 5 illustrate which dipswitch setting corresponds to which channel. Once the receiver channel is altered, make sure to change the transmitter channel as well. The channel on both the transmitter and receiver must be identical in order for the system to work (refer to Section 4.1.2: Transmitter Channel Settings).

Example:



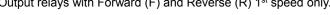
Top position  $\rightarrow$  "1" Bottom position  $\rightarrow$  "0"

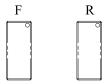
NOTE: The above dipswitch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table on Section 5.

### 4.2.2 Output Relay Configurations

#### 4.2.2.1 Output Relay Types

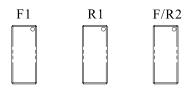
1. 2 output relays per motion – single speed only Output relays with Forward (F) and Reverse (R) 1<sup>st</sup> speed only.





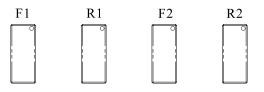
#### 2. 3 output relays per motion – shared 2<sup>nd</sup> speed output relay

Output relays with Forward 1st speed (F1), Reverse 1st speed (R1) and Forward/Reverse 2nd speed (F/R2). Forward and Reverse 2<sup>nd</sup> speed (F/R2) shared the same output relay.



#### 3. 4 output relays per motion – separate 1<sup>st</sup> and 2<sup>nd</sup> speed output relays

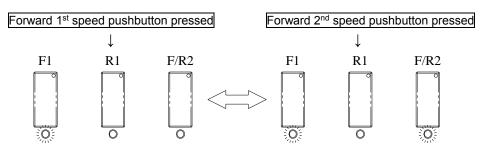
Output relays with Forward 1<sup>st</sup> speed (F1), Reverse 1<sup>st</sup> speed (R1), Forward 2<sup>nd</sup> speed (F2) and Reverse 2<sup>nd</sup> speed (R2). Forward and Reverse 2<sup>nd</sup> speed are separate output relays.



#### 4.2.2.2 Output Relay Actions at 2<sup>nd</sup> Speed

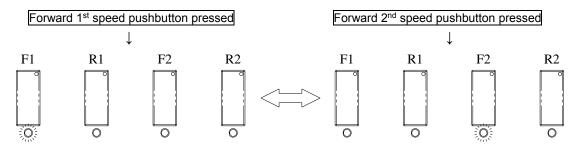
#### 1. 3 output relays configuration with Closed/Closed contact at 2<sup>nd</sup> speed

F1 (or R1) output relay closed at 1<sup>st</sup> speed and F1 + F/R2 (or R1 + F/R2) output relays closed at 2<sup>nd</sup> speed. Refer to Section 4.2.3.1 on how to set to this function.



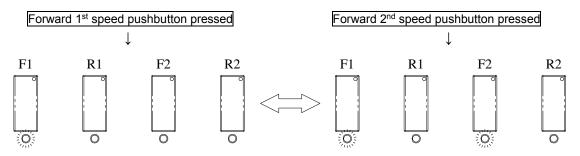
#### 2. 4 output relays configuration with Opened/Closed contact at 2<sup>nd</sup> speed

F1 (or R1) output relay closed at 1<sup>st</sup> speed and F2 (or R2) output relay closed at 2<sup>nd</sup> speed. Refer to Section 4.2.3.1 on how to set to this function.



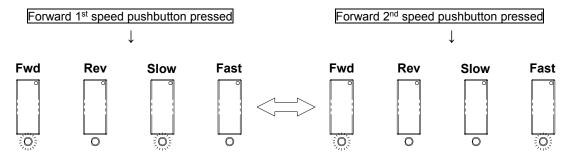
#### 3. 4 output relays configuration with Closed/Closed contact at 2<sup>nd</sup> speed

F1 (or R1) output relay closed at 1<sup>st</sup> speed and F1 + F2 (or R1 + R2) output relays closed at 2<sup>nd</sup> speed. Refer to Section 4.2.3.1 on how to set to this function.

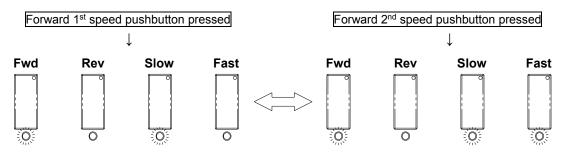


#### 4. 4 output relays configuration with Slow and Fast output relays (Type A)

Fwd (or Rev) + Slow output relays closed at 1<sup>st</sup> speed and Fwd (or Rev) + Fast output relays closed at 2<sup>nd</sup> speed. Refer to Section 4.2.3.1 on how to set to this function.

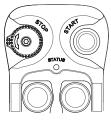


### **5. 4 output relays configuration with Slow and Fast output relays (Type B)** Fwd + Slow (or Rev + Slow) output relays closed at 1<sup>st</sup> speed and Fwd + Slow + Fast (or Rev + Slow + Fast) output relays closed at 2<sup>nd</sup> speed. Refer to Section 4.2.3.1 on how to set to this function.



#### 4.2.2.3 START + AUX Function

After initiating the START function at transmitter startup the same START button becomes an auxiliary function with momentary contact connected through the K30 Function output relay. There are other types of auxiliary functions made available for K25, K26, and K30 Function output relays (refer to Section 4.2.7). Please contact a Magnetek representative if your application requires other types of auxiliary functions connected to these Function output relays.



#### 4.2.2.4 ON/OFF Pushbutton Function

The user can set any of the two adjacent pushbuttons on the transmitter to behave like a mechanical ON & OFF rocker or toggle switch. ON output relay closes when the ON pushbutton is pressed (OFF output relay opens), and OFF output relay closes when the OFF pushbutton is pressed (ON output relay opens). Refer to Section 4.2.3.1 on how to set to this function.

#### 4.2.2.5 Brake Function

When the transmitter pushbutton is released from 2<sup>nd</sup> speed up to 1<sup>st</sup> speed, both 1<sup>st</sup> and 2<sup>nd</sup> speed output relays will open for up to 1 second and then with 1<sup>st</sup> speed output relay closed thereafter. Refer to Section 4.2.3.1 on how to set to this function.

#### 4.2.2.6 External Warning Function

The user can install an external warning device (rotating lights, horn, etc.) to the K26 Function output relay located inside the receiver. The user can choose which pushbutton pair (or pairs) triggers the external warning device when pressed. Refer to Section 4.2.3.1 on how to set to this function.

#### 4.2.2.7 Momentary Contact

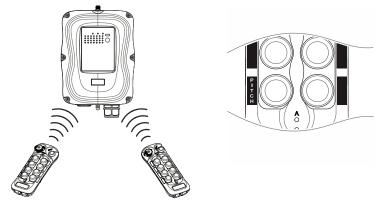
When the pushbutton is released, the corresponding output relay will open or deactivate. This type of relay action usually applies to external applications such as a horn and buzzer. Refer to Section 4.2.3.2 on how to set to this function.

#### 4.2.2.8 Toggled Contact

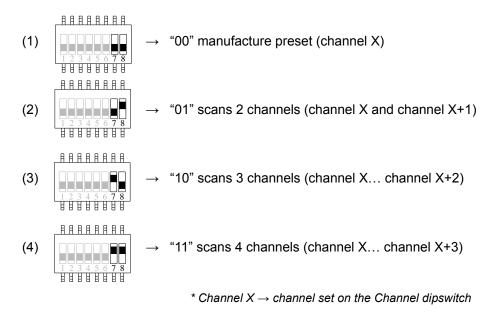
When the pushbutton is released, the corresponding output relay will maintain contact or closure until next time the user presses the same pushbutton again. This type of relay action usually applies to external applications such as lights. Refer to Section 4.2.3.2 on how to set to this function.

#### 4.2.2.9 Pitch & Catch Function

This function allows two operators to control one crane from opposite ends of a cross or long travel. When set to "Pitch & Catch" make sure the second transmitter is set to the next upper channel (channel X+1). For example, if the system is set to channel 01, then the newly added second transmitter must be set to channel 02 and with an identical serial number. Furthermore, the channel dipswitch position #7 and #8 on the RF/decoding board must set to "10" for 2-channel scanning (scans channel 01 and 02). Refer to Sections 4.2.2.10 and 4.2.3.2 on how to set to this function.



#### 4.2.2.10 Receiver Channel Scanning Function

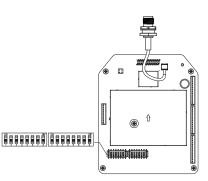


*Example:* If the first six dipswitch positions are set to channel 01 (000001), when set to 2-channel scanning (type-2 above) the receiver will only scan channel 01 and 02.

### 4.2.3 Dipswitch Settings

#### 4.2.3.1 Interlocked Pushbutton Pair

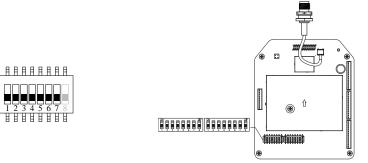
Interlocked means any pushbutton pair cannot be pressed simultaneously, as that pair will cancel the other pair out. Interlocked setting usually applies to an electric motor's forward and reverse motion and On/Off switches. Each dipswitch on the RF/decoder board corresponds to a pushbutton pair.



Dip Settings	Function Descriptions	# of Relays Used
00000000	Single speed only	2
00000010	4 output relays Closed/Closed relay action at 2 <sup>nd</sup> speed (separate 2 <sup>nd</sup> speed output relays)	4
00000100	3 output relays Closed/Closed relay action at 2 <sup>nd</sup> speed (shared 2 <sup>nd</sup> speed output relay)	3
00000110	4 output relays Opened/Closed relay action at 2 <sup>nd</sup> speed (separate 2 <sup>nd</sup> speed output relays)	4
00001000	Forward (or Reverse) + Fast output relays engaged at 2 <sup>nd</sup> speed	4
00001010	Forward (or Reverse) + Slow + Fast output relays engaged at 2 <sup>nd</sup> speed	4
00001100	On (right button) & Off (left button)	2
00010010	00010010 On + Start/Off + Start - For added safety, you must first On or Off pushbutton to activate the output relay.	
00010100	FWD/REV toggled (latching)	2
00100000	Single speed + External warning*	2
00100010	4 output relays Closed/Closed relay action + External warning*	4
00100100	3 output relays Closed/Closed relay action + External warning*	3
00100110	4 output relays Opened/Closed relay action + External warning*	4
01000010	4 output relays Closed/Closed relay action + Brake	4
01000100	3 output relays Closed/Closed relay action + Brake	3
01000110	4 output relays Opened/Closed relay action + Brake	4

#### 4.2.3.2 Non-Interlocked Pushbutton Pair

Non-interlocked setting allows the pushbutton pair(s) be pressed simultaneously. It usually applies to the equipment's auxiliary functions such as lights, horns, or buzzers. Each dipswitch on the RF/decoder board corresponds to a pushbutton pair. Only the first seven dipswitch positions are used (counting from left to right); the eighth dipswitch position (far right) is not used.

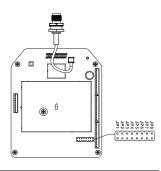


Function Code	Dip Position #1	Dip Position #2 ~ #4 (left button) & #5 ~ #7 (right button)	Function Description
А	1	000	Normal (momentary) contact
В	1	001	Toggled (latching) contact
с	1	100	Normal + Start function - For added safety, you must first press and hold the START button and then press the intended pushbutton to activate the output relay.
D	1	110	Pitch & Catch
E	1	111	2 steps with Closed/Closed relay action

Example #1: Left button (set to function code A) / right button (set to function code B)  $\rightarrow$  **1 000 001** Example #2: Left button (set to function code C) / right button (set to function code D)  $\rightarrow$  **1 100 110** 

### 4.2.4 Jumper Settings

Jumper setting applies to functions such as the standard or reversed logic A/B selector sequence, cable-free configurations, transmitter inline pushbutton configurations, firmware version, system testing and remote pairing methods.



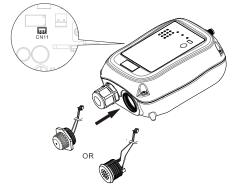
Jumper Settings	Function
JP2 (Inserted)	Pressing the START button is required when receiver MAIN relays are deactivated (cancels ANY button setting on Section 4.1.4).
JP3 (Opened)	Standard A/B selector sequence - Output relay A activated at A position, output relay B activated at B position, both relays activated at A+B position.
JP3 (Inserted)	<b>Reversed logic A/B selector sequence</b> - Output relay B activated at A position, output relay A activated at B position, both relays deactivated at A+B position.
JP6 (Inserted)	Display system firmware version
JP7 (Inserted)	For system testing only (receiver MAIN relays disabled)
JP8 (Opened)	Receiver-to-transmitter remote pairing (pressing the Pairing button required)
JP8 (Inserted)	Receiver-to-transmitter remote pairing (pressing the Pairing button not required)

## 4.2.5 Fuse Ratings

FUSE #	110~120VAC	220~240VAC	380~400VAC	410~460VAC	24VAC	42 & 48VAC	9~36VDC
F3 ~ F10	5.0A	5.0A	5.0A	5.0A	5.0A	5.0A	5.0A
F1 ~ F2	0.5A	0.5A	0.5A	0.5A	1.0A	1.0A	2.0A

### 4.2.6 Lights Indicator and Buzzer Installation

The miniature lights indicator and buzzer can be easily fitted onto the receiver enclosure. When installing a buzzer or light kit, be sure to wire into the K25 relay. If the buzzer is installed it will sound for up to 3 seconds when the START button is initially pressed. The same START button becomes a momentary output thereafter. Also, the buzzer will be activated whenever the receiver MAIN relays are activated. If the light kit is installed, it will need to be set to so that the indicator light will remain active anytime the MAIN relays are active as well. Please contact a Magnetek representative if you would like the lights indicator or the buzzer to work differently than described above.



## 4.2.7 Other Function Output Relays Settings

Listed below are other types of functions that can be outputted through the Function output relay (K25) via the infrared IR programmer unit (manufacture preset to HORN function). Please contact a Magnetek representative for more details.

LV	:	Function relay closes when receiver voltage is low.
ID	:	Function relay works simultaneously with all motion commands.
NORMAL	:	START function + AUX with normal momentary output.
TOGGGLE	:	START function + AUX with toggled/latching output.
EXT	:	Function relay works simultaneously with the receiver MAIN relays.
HORN	:	Function relay closes for up to 3 seconds when START command is initiated a
		transmitter power on and then becomes a normal momentary output thereafter

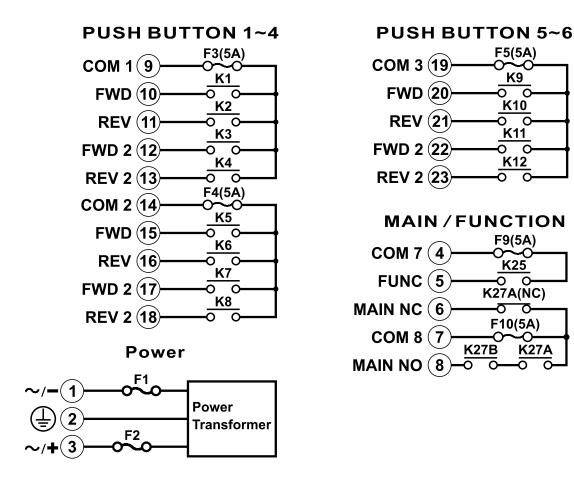


<u> </u>	System Un			
Channel	Dipswitch Setting	Channel	Dipswitch Setting	
01	000001	32	100000	
02	000010	33	100001	
03	000011	34	100010	
04	000100	35	100011	
05	000101	36	100100	
06	000110	37	100101	
07	000111	38	100110	
08	001000	39	100111	
09	001001	40	101000	
10	001010	41	101001	
11	001011	42	101010	
12	001100	43	101011	
13	001101	44	101100	
14	001110	45	101101	
15	001111	46	101110	
16	010000	47	101111	
17	010001	48	110000	
18	010010	49	110001	
19	010011	50	110010	
20	010100	51	110011	
21	010101	52	110100	
22	010110	53	110101	
23	010111	010111 54		
24	011000	55	110111	
25	011001	56	111000	
26	011010	57	111001	
27	011011	58	111010	
28	011100	59	111011	
29	011101	60	111100	
30	011110	61	111101	
31	011111	<b>62</b> 111110		

## **5 System Channels Table**

## 6 Receiver Installation

## 6.1 Output Relay Contact Diagrams



- \* For 9~36VDC power supply, wire #1 corresponds to the negative charge (-) and wire #3 corresponds to the positive charge (+), wire #2 is GROUND.
- \* If PB6 is set to A/B pushbutton select function, connect output A to K10 and output B to K12. Refer to Section 4.1.8.2 on how to set to this function.

## 6.2 Pre-installation Precautions

- 1. Make sure the transmitter and receiver have identical serial numbers and channels.
- 2. Make sure the receiver is not set to the same channel as any other systems in use in the surrounding area.
- 3. Make sure the crane or equipment is working properly prior to installation.
- 4. Make sure the power source to the receiver is set correctly.
- 5. Switch off the main power source to the crane or equipment prior to installation.

C

C

C

C

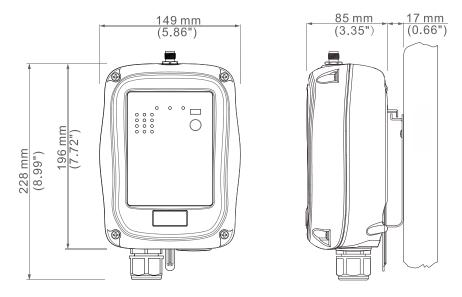
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**K27**A

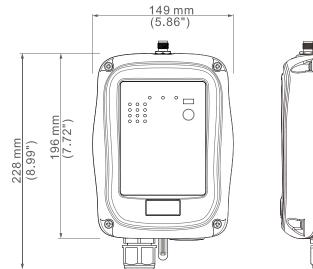
n

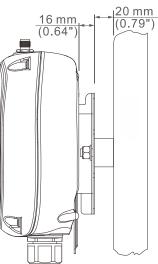
## 6.3 Step-By-Step Installation



#### Mounting Bracket Type 1

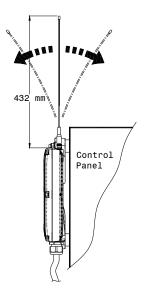
Mounting Bracket Type 2





- 1. For best reception, the location of the receiver should be visible to the operator at all time.
- The location selected should not be exposed to high levels of electric noise. Mounting the receiver next to an unshielded variable frequency drive may cause radio interference. Always locate the receiver as far away from variable frequency drives and electric motors as possible.
- 3. Ensure the selected location has adequate space to accommodate the receiver. If an external antenna is used, to avoid the possibility of antenna damage, always locate the receiver where the antenna is free from any obstacles.
- 4. When installing an external antenna make sure the MCX jack located on the RF/decoder board inside the receiver is connected and jumper set to "EXT" position.



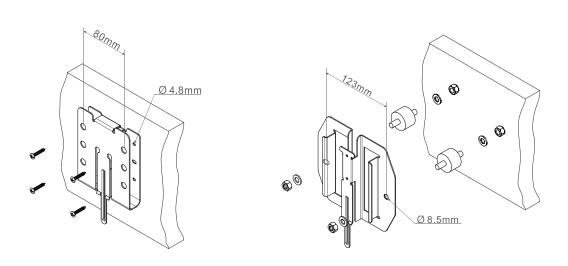


5. For better reception, make sure the receiver is in an upright position.

Mounting Bracket Type 1

- 6. Drill four holes for mounting bracket type 1 and two holes for mounting bracket type 2 on the control panel, wall, or location where the receiver is to be installed.
- 7. Make sure the screws, bolts, or shock absorbers are tightened after installation (not provided with the system).

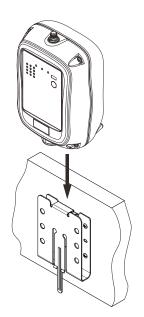
Mounting Bracket Type 2



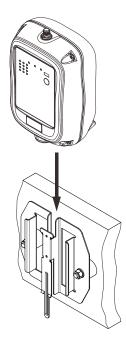
- 8. Slide down the receiver along the guided track to secure the receiver to the mounting bracket.
- 9. Remove the receiver by pressing down the bracket release and pull the receiver upward until it clears the guided track.

#### Install

Mounting Bracket Type 1



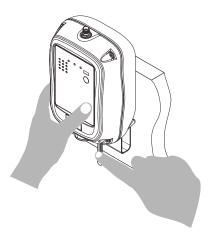
Mounting Bracket Type 2

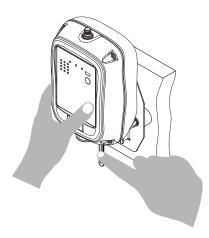


Remove

Mounting Bracket Type 1

Mounting Bracket Type 2

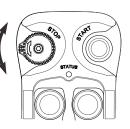




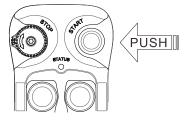
## **7 Operating Procedures**

## 7.1 General Operation

 Reset the STOP button located on the top left hand corner of the transmitter by rotating it clockwise or counter clockwise; the button will pop up. The transmitter is powered on when the STOP button is elevated.



- b) After turning on the transmitter power, check the Status LED on the transmitter for any sign of system irregularities (refer to Section 7.5.1: Transmitter Status Indications). If the transmitter is in good working order, the Status LED will blink green for up to two seconds at startup (no faults detected).
- c) Press the START button for up to one second to activate the receiver MAIN relays. The same START button becomes an auxiliary function thereafter (refer to Section 4.2.2.3: START + AUX Function). Then press any pushbutton on the transmitter to begin operation. Pressing any pushbutton prior to initiating the START command at startup will result in no signals transmitted (Status LED blinks orange).



- d) In case of an emergency, press down the STOP button to disconnect the receiver MAIN relays and the transmitter power. To resume operation, rotate the STOP button clockwise or counter clockwise; the button will pop up. Then press the START button for up to 1 second to reconnect the receiver MAIN relays. For safety, pressing the START button is strictly required every time when the transmitter is turned on or after every STOP button reset.
- e) After one minute or five minutes of inactivity (pushbutton not pressed) the receiver MAIN relays are temporarily disconnected (refer to Section 4.1.5: Transmitter Inactivity Timer Settings). Press any pushbutton or the START button to resume operation (refer to Section 4.1.4: Transmitter Start Function Settings). The receiver MAIN relays are also temporarily disconnected when the system encounters strong radio interference, dead spots, low battery condition, and/or when the system is out of operating range.
- f) Turn off the transmitter power by pressing down the STOP button; it will disconnect the transmitter power and the receiver MAIN relays altogether.

## 7.2 A/B Pushbutton Select Operation

Pressing the "A/B" pushbutton repeatedly toggles between output relay A, B and A+B respectively. There are four different types of Select A/B sequences available (refer to Section 4.1.8.2).

**Standard** – Output relay A activated at A position, output relay B activated at B position, both output relays activated at A+B position.

**Reversed logic** - Output relay A activated at B position, output relay B activated at A position, both output relays deactivated

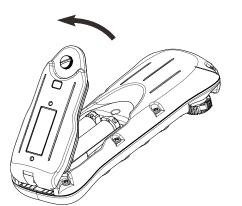
at A+B position. Refer to Section 4.2.4: Jumper Settings.

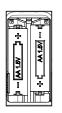
## 7.3 Pitch & Catch Operation

Press the "PITCH" pushbutton for up to 2 seconds to release control of the receiver. Press the START button for up to 1 second to gain control of the receiver. The second operator is unable to take control of the receiver unless the first operator presses the "PITCH" pushbutton. Refer to Section 4.2.2.9 and Section 4.2.3.2 on how to set to this function.

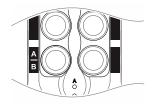
## 7.4 Changing Batteries

Change the transmitter batteries ("AA" alkaline battery x 2) by unscrewing the battery cover located on the backside of the transmitter. During battery installation make sure the batteries are installed correctly, with "+" to "+" charge and "–" to "–" charge. Also make sure the screw is tightened after battery installation to avoid water, moisture, dirt, grease, and other liquid penetration.









## 7.5 System Status Light Indications

## 7.5.1 Transmitter Status Indications

Туре	Display Type	Indication
1	Constant red	Voltage below 1.9V at initial power on (transmitter power and receiver MAIN relays shut off)
1	Constant red	Voltage below 1.8V during operation (transmitter power and receiver MAIN relays shut off)
2	1 red blink followed by a 2-second pause	Voltage below 1.85V during operation (change batteries suggested)
3A	2 red blinks followed by a 2-second pause	Defective or jammed pushbutton detected at initial power on
3В	No light displayed	When defective pushbutton condition occurs (2 red blinks, type 3A above), find out which pushbutton is defective by pressing all of them one at a time. If the pushbutton is in good working order when pressed, the Status LED is off. If the Status LED maintained 2 red blinks then the pushbutton is defective.
4	4 red blinks followed by a 2-second pause	Transmitter is unable to lock onto the assigned channel
5	Constant green for up to 2 seconds	Transmitter power on with no faults detected
6	Blinking green	Transmission in progress
7	Blinking orange	Pressing any pushbutton prior to initiating the START command at power on

Туре	Display Type (Green & Red)	Indication
1	Fast green blinks	Decoding in process
2	Slow green blinks	Decoding on standby
3	2 red blinks	Receiver MAIN relays jammed or defective
4	3 red blinks	Decoding processors defective
5	4 red blinks	Receiving RF defective
6	Fast red blinks	Incorrect transmitter serial number
7	Constant red	Receiver low voltage
8	No light displayed	Decoding processors defective

## 7.5.2 Receiver Status Indications

### 7.5.3 Receiver Power Indications

Туре	Display Type (Red)	Indication
1	On	Power to receiver
2	Off	No power to receiver

### 7.5.4 Receiver COM Indications

Туре	Display Type (Red)	Indication
1	On	Power to relay Board
2	Off	No power to relay board

## **8 General Specifications**

Frequency Range	:	433.050MHz ~ 434.575MHz
Number of Channels	:	62 channels
Channel Spacing	:	25 KHz
Modulation	:	Digital Frequency Modulation based
		on Manchester Code, 20bit address,
		32bit CRC and Hamming Code.
Encoder & Decoder	:	Microprocessor-controlled
Transmitting Range	:	>100 Meters (300 feet)
Hamming Distance	:	>6
Frequency Control	:	Synthesized PLL
Receiver Type	:	Frequency Auto Scanning
Receiver Sensitivity	:	-116dBm
Spurious Emission	:	-50dB
Antenna Impedance	:	50 ohms
Responding Time	:	40mS (average)
Transmitting Power	:	5.0mW
Enclosure Type	:	NEMA4
Enclosure Rating	:	IP66
Output Contact Rating	:	250V @ 8 Amps
Transmitter Operating Voltage	:	3.0VDC
Receiver Power Consumption	:	3~7VA
Available Receiver Voltages	:	9~36VDC
		24VAC
		42VAC
		48VAC
		110~120VAC
		220~240VAC
		380~400VAC
		410~460VAC
Operating Temperature	:	-25°C ~ 75°C / -13°F ~ 167°F
Transmitter Dimension	:	141mm (L) x 69mm (W) x 38mm (H)
Receiver Dimension	:	196mm (L) x 149mm (W) x 85mm (H)
Transmitter Weight	:	203g / 7.2oz (include batteries)
Receiver Weight	:	1.5kg / 3.3lb (include output cable)
5		5 (

## **C E U Declaration of Conformity C E** (EMC, R&TTE, SAFETY & MACHINERY)

#### For the following equipment:

Product	:	Flex ECO (Base) Series Radio Remote Control System
Multiple Listee Model No.	:	Flex ECO (Base) 4S/4X, ECO (Base) 8S/8X,
		ECO (Base) 12S/12X
Manufacturer's Name	:	Advanced Radiotech Corporation
Manufacturer's Address :	:	1F, 288-1, Hsin Ya Road, Chien Chen District,
		Kaohsiung, Taiwan

We hereby declare, that all major safety requirements, concerning the CE Mark Directive 2006/42/EC and Low Voltage Directive 2006/95/EC, Electromagnetic Compatibility Directives 2004/108/EC, R&TTE Directive 1999/5/EC are fulfilled, as laid out in the guideline set down by the member states of the EEC Commission.

## The standards relevant for the evaluation of the electrical safety requirements are as follow:

EMC	:	EN 301 489-1 + EN 301 489-3
R&TTE	:	EN 300 220-1 V2.3.1 + EN 300 220-2 V2.3.1
SAFETY	:	EN 60950:2006+A1+A11+A12
MACHINERY	:	EN 60204-32:2008, EN 13557:2003+A1:2008
		EN ISO 13849-1:2008 (PL=d), EN 60529 (IP66)

#### Test reports issued by:

EMC	:	SGS
R&TTE	:	SGS
SAFETY	:	SGS
MACHINERY	:	SGS

#### Person responsible for marking this declaration:

5200 Tom Jou / President

Name and signature of authorized person